

Graphical CSS Code Transformation Using ZX Calculus

by

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Author's Declaration

This thesis consists of material all of which I authored or co-authored: see Statement of Contributions included in the thesis. This is a true copy of the thesis, including any required final revisions, as accepted by my examiners.

I understand that my thesis may be made electronically available to the public.

Statement of Contributions

- Chapter 1 reviews the background and the proceeding results for our research.
- Chapter 2 introduces the notions and techniques used to graphically transform different CSS codes using the ZX calculus. This is based on Kissinger’s ZX normal form proposed in [57].
- Chapter 3 generalizes the ZX normal form for CSS stabilizer codes to CSS subsystem codes. It also provides bidirectional rewrite rules for any CSS encoder. This technique was proposed by Jiaxin Huang and myself.
- Chapter 4 provides explicit graphical derivations for morphing the Steane and the quantum Reed-Muller codes. This scheme was initially proposed by Michael Vasmer [92]. The graphical interpretation was proposed by Lia Yeh. The edge cases were proposed by myself.
- Chapter 5 focuses on the switching protocol between the Steane code and the quantum Reed-Muller code. Through the ZX calculus, we provide a graphical interpretation of this protocol as gauge-fixing the $[[15, 1, 3, 3]]$ subsystem code, followed by syndrome-determined recovery operations. The idea of using a different fault-tolerant protocol (i.e., code-switching) rather than the magic state distillation was originally brought up by my supervisor, Michele Mosca. Aleks Kissinger encouraged us to explore the connections between code-switching and subsystem code gauge-fixing. To answer this question, I visualized both protocols using the ZX diagrams and showed that they are different interpretations of the same measurement-based procedure.
- Chapter 6 concludes our work and proposes future directions. This is based on the discussions among all co-authors.

The research deliverable in this thesis is the joint work of all co-authors.

Abstract

In this work, we present a generic approach to transform CSS codes by building upon their equivalence to phase-free ZX diagrams. Using the ZX calculus, we demonstrate diagrammatic transformations between encoding maps associated with different codes. As a motivating example, we give explicit transformations between the Steane code and the quantum Reed-Muller code, since by switching between these two codes, one can obtain a fault-tolerant universal gate set. To this end, we propose a bidirectional rewrite rule to find a (not necessarily transversal) physical implementation for any logical ZX diagram in any CSS code.

We then focus on two code transformation techniques: *code morphing*, a procedure that transforms a code while retaining its fault-tolerant gates, and *gauge fixing*, where complimentary codes can be obtained from a common subsystem code (e.g., the Steane and the quantum Reed-Muller codes from the $[[15, 1, 3, 3]]$ code). We provide explicit graphical derivations for these techniques and show how ZX and graphical encoder maps relate several equivalent perspectives on these code-transforming operations.

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First and foremost, I wish to thank my supervisor Michele Mosca for his guidance, insights, and unwavering support. When I joined Waterloo in 2021, I was a bit burned out from a very intensive undergrad and didn't know how to research as a graduate student. He never rushed me and allowed me to explore at my own pace. I could not think of a better time for me to stand on my own feet and navigate a research problem independently. It is a privilege to learn more from Michele and work with him. He trained me to present a research problem efficiently and showed me the importance of taking initiative. He challenged me with interesting problems and trusted me to conquer them. He taught me to research with a pragmatic mindset and nudged me to reason thoroughly. He encouraged me to see the bigger world and inspired me to stay grounded. Dear Michele, thank you for having faith in me. I am, and will continuously be driven by it.

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Preface

Under the guidance of my supervisor Michele Mosca, my Master’s research focuses on the algebraic and graphical methods for fault-tolerant quantum compilation. This encompasses three key ingredients. Firstly, characterize an ideal quantum system through the lens of algebra and the ZX calculus. Next, define and optimize a cost function for a logical quantum circuit. Based on the hardware and algorithm specifics, these insights help us tailor strategies to optimize resources in quantum computation.

A few months into the program, we started to realize that for me to really understand various aspects of quantum compiling, there is no alternative to solving different compilation-related problems and acquiring essential skills. I am very fortunate to learn from experts in the field. Over the past two years, our collaborations have led to novel and interesting results.

- [1] Meijer-van de Griend, A., & **Li, S. M.** (2022). Dynamic Qubit Allocation and Routing for Constrained Topologies by CNOT Circuit Re-Synthesis. In Quantum Physics and Logic. Electronic Proceedings in Theoretical Computer Science. [arXiv preprint arXiv:2205.00724](#).
- [2] Amy, M., Glaudell, A. N., **Li, S. M.**, & Ross, N. J. (2023). Improved Synthesis of Toffoli-Hadamard Circuits. [arXiv preprint arXiv:2305.11305](#).
- [3] Huang, J., **Li, S. M.**, Yeh, L., Kissinger, A., Mosca, M., & Vasmer, M. (2023). Graphical CSS Code Transformation Using ZX Calculus. [arXiv preprint arXiv:2307.02437](#).
- [4] Kim, D., Kim, M., **Li, S. M.**, & Mosca, M. (2023). Improving the Fidelity of CNOT Circuits on NISQ Hardware (To appear in arXiv).
- [5] **Li, S. M.**, Mosca, M., Ross, N. J., & Zhao, Y. (2024). Generators and Relations for N-Qutrit Clifford Operators (Manuscript in preparation).
- [6] Huang, J., Kissinger, A., **Li, S. M.**, Mosca, M., Vasmer, M., & Yeh, L. (2024). A Unified Framework for Stabilizer Code Encoders Using ZX Calculus (Manuscript in preparation).

In the meantime, the training at Waterloo exposed me to fault-tolerant protocols based on different quantum error-correcting schemes. Lectures and seminars deepened my understanding of prevalent quantum algorithms and the fundamental complexity theory. Additionally, I learned algebraic and graph-theoretic techniques for quantum circuit optimization. My internship with PsiQuantum and numerous research discussions also helped me put everything in perspective. I started to appreciate quantum compilation beyond an isolated theoretical problem.

In this thesis, we focus on one of our published works in 2023, *Graphical CSS Code Transformation Using ZX Calculus*. This project is very special to me as it highlights my first adventure into the ZX calculus and quantum error-correcting codes. This is also the first project where I initiated the core ideas and took the lead throughout the collaboration.

Chapter 1

Introduction

Quantum computation has demonstrated its potential in speeding up large-scale computational tasks [4, 100] and revolutionizing multidisciplinary fields such as drug discovery [21], climate prediction [89], chemistry simulation [69], and the quantum internet [38]. However, in a quantum system, qubits are sensitive to interference and information becomes degraded [73]. To this end, quantum error correction [82, 84] and fault tolerance [47, 58] have been developed to achieve large-scale universal quantum computation [48].

Stabilizer theory [46] is a mathematical framework to describe and analyze properties of quantum error-correcting codes (QECC). It is based on the concept of stabilizer groups, which are groups of Pauli operators whose joint $+1$ eigenspace corresponds to the code space. Stabilizer codes are a specific type of QECC whose encoder can be efficiently simulated [1, 45]. As a family of stabilizer codes, Calderbank-Shor-Steane (CSS) codes permit simple code constructions from classical codes [17, 18, 84, 86].

As a language for rigorous diagrammatic reasoning of quantum computation, the ZX calculus consists of ZX diagrams and a set of rewrite rules [27, 91]. It has been used to relate stabilizer theory to graphical normal forms: notably, efficient axiomatization of the stabilizer fragments for qubits [5, 51, 72], qutrits [90, 95], and prime-dimensional qudits [12]. This has enabled various applications, such as measurement-based quantum computation [72, 83], quantum circuit optimization [30, 43] and verification [68], as well as classical simulation [25, 57]. Beyond these, ZX-calculus has been applied to verify QECC [36, 39], represent Clifford encoders [54], as well as study various QECC such as tripartite coherent parity check codes [22, 24] and surface codes [40, 41, 42, 81]. Specific to CSS codes, ZX-calculus has been used to visualize their encoders [55], code maps and code surgeries [33], their correspondence to affine Lagrangian relations [31], and their constructions in high-dimensional quantum systems [32].

In this thesis, we seek to answer some overarching questions about QECC constructions and fault-tolerant implementations. We focus on CSS codes and leverage the direct correspondence between phase-free ZX diagrams and CSS code encoders [55]. Given an arbitrary CSS code, based on its normal form, we propose a bidirectional rewrite rule to find a (not necessarily transversal) physical implementation for any logical ZX diagram. Furthermore, we demonstrate diagrammatic transformations between encoding maps associated with different codes. Here, we focus on two code transformation techniques: *code*

morphing, a procedure that transforms a code while retaining its fault-tolerant gates [92], and *gauge fixing*, where complimentary codes (such as the Steane and the quantum Reed-Muller codes) can be obtained from a common subsystem code [3, 74, 77, 94]. We provide explicit graphical derivations for these techniques and show how ZX and graphical encoder maps relate several equivalent perspectives on these code transforming operations.

Chapter 2

Preliminaries

We start with some definitions. The Pauli matrices are 2×2 unitary operators acting on a single qubit. Let i be the imaginary unit.

$$I = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}, \quad X = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}, \quad Z = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}, \quad Y = iXZ = \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix}.$$

Let \mathcal{P}_1 be the single-qubit Pauli group, $\mathcal{P}_1 = \langle i, X, Z \rangle$, $I, Y \in \mathcal{P}_1$.

2.1 The Stabilizer Formalism and CSS Codes

Definition 1. Let $U \in \mathcal{U}(2)$. In a system over n qubits, $1 \leq i \leq n$,

$$U_i = I \otimes \dots \otimes I \otimes U \otimes I \otimes \dots \otimes I$$

denotes U acting on the i -th qubit, and identity on all other qubits.

Let \mathcal{P}_n be the n -qubit Pauli group. It consists of all tensor products of single-qubit Pauli operators.

$$\mathcal{P}_n = \langle i, X_1, Z_1, \dots, X_n, Z_n \rangle.$$

The stabilizer formalism is a mathematical framework to describe and analyze the properties of certain QECC, called stabilizer codes [46, 47]. Consider n qubits and let $m \leq n$. A stabilizer group $\mathcal{S} = \langle S_1, \dots, S_m \rangle$ is an Abelian subgroup of \mathcal{P}_n that does not contain $-I$. The codespace of the corresponding stabilizer code, \mathcal{C} , is the joint $+1$ eigenspace of \mathcal{S} , i.e.,

$$\mathcal{C} = \{|\psi\rangle \in \mathbb{C}^{2^n}; S|\psi\rangle = |\psi\rangle, \forall S \in \mathcal{S}\}.$$

The number of encoded qubits in a stabilizer code is $k = n - m$, where m is the number of independent stabilizer generators [46]. Moreover, we can define the *centralizer* of \mathcal{S} as

$$\mathcal{N}(\mathcal{S}) = \{U \in \mathcal{P}_n; [U, S] = 0, \forall S \in \mathcal{S}\}.$$

One can check that $\mathcal{N}(\mathcal{S})$ is a subgroup of \mathcal{P}_n and $\mathcal{S} \subset \mathcal{N}(\mathcal{S})$. We remark that the notions of normalizer and centralizer coincide for any stabilizer group. In what follows, we will use them interchangeably. As we will see later, $\mathcal{N}(\mathcal{S})$ provides an algebraic structure for the subsystem codes. The code distance, d , of a stabilizer code is the minimal weight of operators in $\mathcal{N}(\mathcal{S})/\langle iI \rangle$ that is not in \mathcal{S} . We summarize the properties of a stabilizer code with the shorthand $\llbracket n, k, d \rrbracket$.

Finally, we introduce some notation for subsets of n -qubit Pauli operators, which will prove useful for defining CSS codes.

Definition 2. Let M be an $m \times n$ binary matrix and $P \in \mathcal{P}_1/\langle iI \rangle$. In the stabilizer formalism, M is called the stabilizer matrix, and M^P defines m P -type stabilizer generators.

$$M^P := \left\{ \bigotimes_{j=1}^n P^{[M]_{ij}}; 1 \leq i \leq m \right\}.$$

CSS codes are QECC whose stabilizers are defined by two orthogonal binary matrices G and H [17, 84]:

$$\mathcal{S} = \langle G^X, H^Z \rangle, \quad GH^\top = \mathbf{0},$$

H^\top is the transpose of H . This means that the stabilizer generators of a CSS code can be divided into two types: X-type and Z-type. For example, the $\llbracket 7, 1, 3 \rrbracket$ Steane code [84] in Figure 2.1a is specified by

$$G = H = \begin{bmatrix} 1 & 0 & 1 & 0 & 1 & 0 & 1 \\ 0 & 1 & 1 & 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 1 & 1 & 1 & 1 \end{bmatrix}_{3 \times 7}. \quad (2.1)$$

Accordingly, the X-type and Z-type stabilizers are defined as

$$\begin{aligned} S_1^X &= X_1 X_3 X_5 X_7, & S_2^X &= X_2 X_3 X_6 X_7, & S_3^X &= X_4 X_5 X_6 X_7 \\ S_1^Z &= Z_1 Z_3 Z_5 Z_7, & S_2^Z &= Z_2 Z_3 Z_6 Z_7, & S_3^Z &= Z_4 Z_5 Z_6 Z_7. \end{aligned}$$

The logical operators \bar{X} and \bar{Z} are defined as

$$\bar{X} = X_1 X_4 X_5 \quad \text{and} \quad \bar{Z} = Z_1 Z_4 Z_5. \quad (2.2)$$

In Section 2.2, we define CSS subsystem codes. In Section 2.3, we define several CSS codes that will be used in subsequent sections. In Section 2.4, we introduce the basics of the ZX calculus and the phase-free ZX normal forms.

2.2 The CSS Subsystem Codes

Subsystem codes [60, 75] are QECC where some of the logical qubits are not used for information storage and processing. These logical qubits are called gauge qubits. By

fixing gauge qubits to some specific states, the same subsystem code may exhibit different properties, for instance, having different sets of transversal gates [10, 62, 63, 74, 99]. This provides a tool to circumvent restrictions on transversal gates such as the Eastin-Knill theorem [37].

Based on the construction proposed in [75], we describe a subsystem code using the stabilizer formalism.

Definition 3. *Given a stabilizer group \mathcal{S} , a gauge group \mathcal{G} is a normal subgroup of $\mathcal{N}(\mathcal{S})$, such that $\mathcal{S} \subset \mathcal{G}$ and that \mathcal{G}/\mathcal{S} contains anticommuting Pauli pairs. In other words, one can write*

$$\mathcal{S} = \langle S_1, \dots, S_m \rangle, \quad \mathcal{G} = \langle S_1, \dots, S_m, g_1^X, g_1^Z, \dots, g_r^X, g_r^Z \rangle, \quad 1 \leq m + r \leq n.$$

$(\mathcal{S}, \mathcal{G})$ defines an $[[n, k, r, d]]$ subsystem code where $n = m + k + r$. The logical operators are elements of the quotient group $\mathcal{L} = \mathcal{N}(\mathcal{S})/\mathcal{G}$.

Under this construction, n physical qubits are used to encode k logical qubits with r gauge qubits. Alternatively, we can think of the gauge group \mathcal{G} as partitioning the code space \mathcal{C} into two subsystems: $\mathcal{C} = \mathcal{A} \otimes \mathcal{B}$. Logical information is encoded in \mathcal{A} and \mathcal{L} serves as the group of logical operations. Gauge operators from \mathcal{G} act trivially on subsystem \mathcal{A} , while operators from \mathcal{L} act trivially on subsystem \mathcal{B} . Therefore, two states $\rho^{\mathcal{A}} \otimes \rho^{\mathcal{B}}$ and $\rho'^{\mathcal{A}} \otimes \rho'^{\mathcal{B}}$ are considered equivalent if $\rho^{\mathcal{A}} = \rho'^{\mathcal{A}}$, regardless of the states $\rho^{\mathcal{B}}$ and $\rho'^{\mathcal{B}}$. When $r = 0$, $\mathcal{G} = \mathcal{S}$. In that case, an $[[n, k, 0, d]]$ subsystem code is essentially an $[[n, k, d]]$ stabilizer code.

CSS subsystem codes are subsystem codes whose stabilizer generators can be divided into X-type and Z-type operators. In what follows, we provide an example to illustrate their construction.

2.3 Some Interesting CSS Codes

We start by defining the stabilizer groups for the $[[7, 1, 3]]$ Steane code, the $[[15, 1, 3]]$ extended Steane code [3], and the $[[15, 1, 3]]$ quantum Reed-Muller code [59]. They are derived from the family of $[[2^m - 1, 1, 3]]$ quantum Reed-Muller codes, with a recursive construction of stabilizer matrices [87]. The Steane code has transversal logical Clifford operators, and the quantum Reed-Muller code has a transversal logical T gate. Together these operators form a universal set of fault-tolerant gates. In Chapter 5, the relations between these codes are studied from a diagrammatic perspective.

For brevity, their corresponding stabilizer groups are denoted as \mathcal{S}_{steane} , \mathcal{S}_{ex} , and \mathcal{S}_{qrm} . As per Definition 2, consider three stabilizer matrices F , H , and J . Note that G is defined in Equation (2.1). $\mathbf{0}$ and $\mathbf{1}$ denote blocks of 0s' and 1s' respectively. Their dimensions can be inferred from the context.

$$F = \begin{bmatrix} G & 0 & G \\ \mathbf{0} & \mathbf{1} & \mathbf{1} \end{bmatrix}_{4 \times 15}, \quad H = [G \quad \mathbf{0}]_{3 \times 15},$$

$$J = \begin{bmatrix} 1 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 \end{bmatrix}_{3 \times 15}.$$

Then, the stabilizer groups are defined as

$$\mathcal{S}_{steane} = \langle G^X, G^Z \rangle, \quad \mathcal{S}_{ex} = \langle F^X, F^Z, H^X, H^Z \rangle, \quad \mathcal{S}_{qrm} = \langle F^X, F^Z, H^Z, J^Z \rangle. \quad (2.3)$$

Geometrically, one can define \mathcal{S}_{steane} and \mathcal{S}_{qrm} with the aid of Figure 2.1. In Figure 2.1a, the Steane code is visualized on a 2D lattice. Since the Steane code is self-dual, every coloured face corresponds to an X-type and Z-type stabilizer. In Figure 2.1b, the quantum Reed-Muller code is visualized on a 3D lattice. Every coloured face corresponds to a weight-4 Z-type stabilizer. Every coloured cell corresponds to a weight-8 X-type stabilizer. For the Steane code, the logical operators defined in Equation (2.2) correspond to an edge in the triangle. For the quantum Reed-Muller code, the logical X operator corresponds to a weight-7 triangular face, and the logical Z operator corresponds to a weight-3 edge of the entire tetrahedron. An example is shown below.

$$\bar{X} = X_1 X_2 X_3 X_4 X_5 X_6 X_7 \quad \text{and} \quad \bar{Z} = Z_1 Z_4 Z_5 \quad (2.4)$$

Given such representations, the Steane code and the quantum Reed-Muller code are also special cases of colour codes [7, 8, 62].



(a) Visualize the Steane code.

(b) Visualize the quantum Reed-Muller code.

Figure 2.1: Each vertex represents a physical qubit. Each edge serves as an aid to the eye. They do not imply any physical interactions or inherent structures. In Figure 2.1a, the Steane code is visualized as a 2D colour code. In Figure 2.1b, the quantum Reed-Muller code is visualized as a 3D colour code.

From Equation (2.3), the extended Steane code is self-dual, and its encoded state is characterized by the lemma below. It shows that \mathcal{S}_{ex} and \mathcal{S}_{steane} are equivalent up to some auxiliary state.

Lemma 1 ([3]). *Any codeword $|\psi\rangle$ of the extended Steane code can be decomposed into a codeword $|\phi\rangle$ of the Steane code and a fixed state $|\eta\rangle$. That is,*

$$|\psi\rangle = |\phi\rangle \otimes |\eta\rangle,$$

where $|\eta\rangle = \frac{1}{\sqrt{2}}(|0\rangle|\bar{0}\rangle + |1\rangle|\bar{1}\rangle)$, $|\bar{0}\rangle$ and $|\bar{1}\rangle$ are the logical 0 and 1 encoded in the Steane code.

Since the logical information $|\phi\rangle$ encoded in the Steane code is not entangled with $|\eta\rangle$, to switch between the Steane code and the extended Steane code, one may simply add or discard the auxiliary state $|\eta\rangle$. This property will prove useful in Chapter 5.

Next, we define the $[[15, 1, 3, 3]]$ CSS subsystem code [94]. As per Definition 3, let \mathcal{S}_{sub} and \mathcal{G} be its stabilizer group and gauge group respectively.

$$\mathcal{S}_{sub} = \langle F^X, F^Z, H^Z \rangle, \quad \mathcal{G} = \langle F^X, F^Z, H^X, H^Z, J^Z \rangle. \quad (2.5)$$

Let $\mathcal{L}_g = \mathcal{G}/\mathcal{S}$ and $\mathcal{L} = \mathcal{N}(\mathcal{S})/\mathcal{G}$. One can verify that

$$\mathcal{L}_g = \langle H^X, J^Z \rangle, \quad \mathcal{L} = \langle \bar{X}, \bar{Z} \rangle. \quad (2.6)$$

Thus, the CSS subsystem code has one logical qubit and three gauge qubits, and they are acted on by \mathcal{L}_g and \mathcal{L} respectively. From Chapter 3 onwards, we call operators in \mathcal{L}_g as *gauge operators*.

Moreover, \mathcal{S}_{sub} can be viewed as the stabilizer group of a $[[15, 4, 3]]$ CSS code, with logical operators \mathcal{L}' . This code appears in an intermediary step of the gauge fixing process in Chapter 5.

$$\mathcal{L}' := \mathcal{L}_g \cup \mathcal{L} = \langle H^X, J^Z, \bar{X}, \bar{Z} \rangle. \quad (2.7)$$

2.4 The ZX Calculus

The qubit ZX-calculus [26, 27, 28, 91] is a quantum graphical calculus for diagrammatic reasoning of any qubit quantum computation. Every diagram in the calculus is composed of two types of generators: Z spiders, which sum over the eigenbasis of the Pauli Z operator:

$$m \langle \text{Z spider} \rangle_n := |0\rangle^{\otimes n} \langle 0|^{\otimes m} + e^{i\alpha} |1\rangle^{\otimes n} \langle 1|^{\otimes m}, \quad (2.8)$$

and X spiders, which sum over the eigenbasis of the Pauli X operator:

$$m \langle \text{X spider} \rangle_n := |+\rangle^{\otimes n} \langle +|^{\otimes m} + e^{i\alpha} |-\rangle^{\otimes n} \langle -|^{\otimes m}. \quad (2.9)$$

The ZX-calculus is *universal* [27] in the sense that any linear map from m qubits to n qubits corresponds exactly to a ZX diagram, by the construction of Equations (2.8) and (2.9) and the composition of linear maps.

Furthermore, the ZX-calculus is *complete* [49, 53]: Any equality of linear maps on any number of qubits derivable in the Hilbert space formalism, is derivable using only a finite set of rules in the calculus. The smallest complete rule set to date [93] is shown in Figure 2.2.

Some additional rules, despite being derivable from this rule set, will be convenient to use in this paper. They are summarized in Figure 2.3.

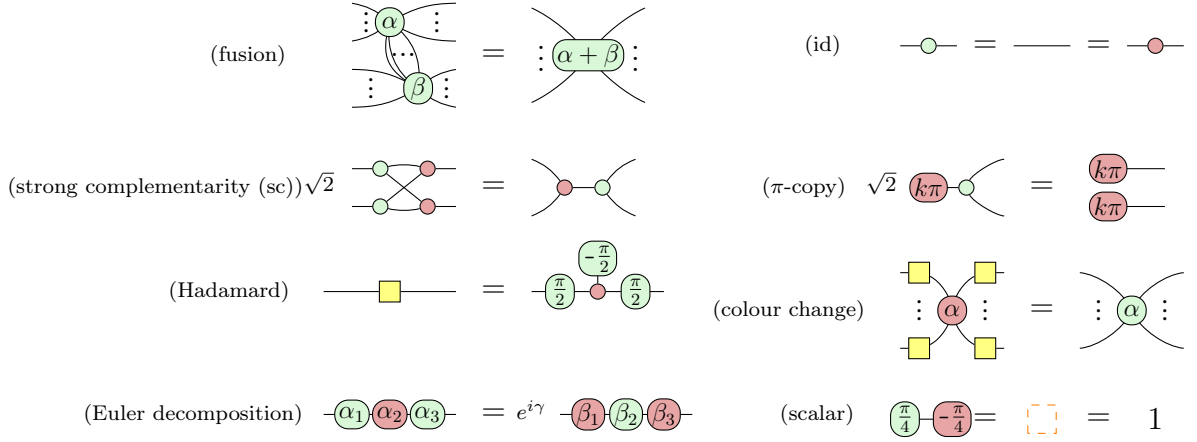


Figure 2.2: These eight equations suffice to derive all other equalities of linear maps on qubits [93]. $k \in \mathbb{Z}_2$. α_i , β_i and γ are real numbers satisfying the trigonometric relations derived in [29]. Each equation still holds when we replace all spiders with their corresponding spiders of the opposite colour. Whenever there are any two wires with ... between them, the rule holds when replacing this with any number of wires (i.e., 0 or greater).

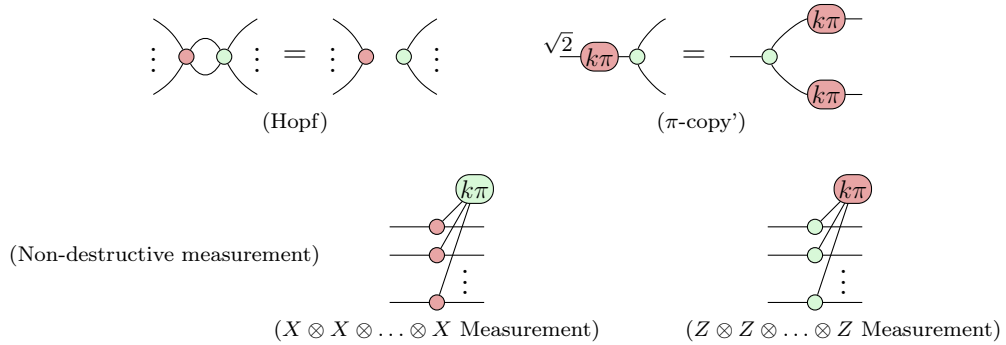


Figure 2.3: Some other useful rewrite rules, each derivable from the rules in Figure 2.2. $k \in \mathbb{Z}_2$. Each equation still holds when we interchange X and Z spiders.

When a spider has phase zero, we omit its phase in the diagram, as shown below. A ZX diagram is *phase-free* if all of its spiders have zero phases. For more discussions on phase-free ZX diagrams, we refer readers to consult [55].



2.5 The ZX Normal Form for CSS Codes

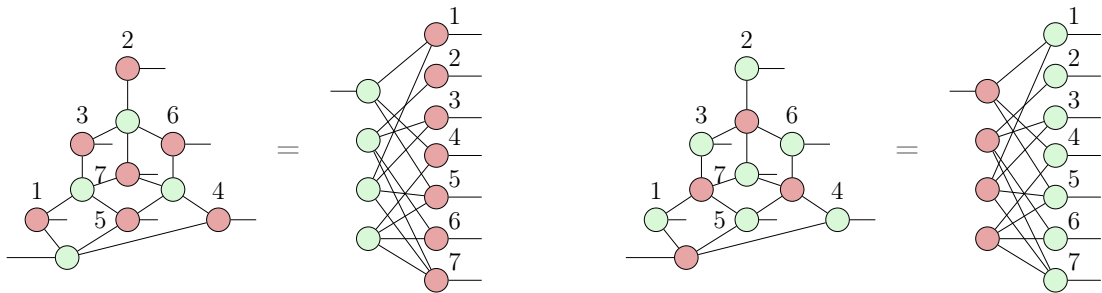
Due to the universality of the ZX calculus, quantum error-correcting code encoders, as linear isometries, can be drawn as ZX diagrams [54]. Moreover, the encoder for a CSS code corresponds exactly to the phase-free ZX (and XZ) normal form [55].

Definition 4. For a CSS stabilizer code defined by \mathcal{S} , let $\{S_i^X; 1 \leq i \leq m_1\} \subset \mathcal{S}$ be the X-type stabilizer generators and $\{\overline{X}_j; 1 \leq j \leq k\}$ be the logical X operators, $m_1 + k < n$. Its ZX normal form can be found via the following steps:

- (a) For each physical qubit, introduce an X spider.
- (b) For each X-type stabilizer generator S_i^X and logical operator \overline{X}_j , introduce a Z spider and connect it to all X spiders where this operator has support.
- (c) Give each X spider an output wire.
- (d) For each Z spider representing \overline{X}_j , give it an input wire.

As an example, the ZX normal form for the Steane code is drawn in Figure 2.4a. The XZ normal form can be constructed based on the Z-type stabilizer generators $\{S_i^Z; 1 \leq i \leq m_2\} \subset \mathcal{S}$ and the logical Z operators $\{\overline{Z}_j; 1 \leq j \leq k\}$ by inverting the roles of X and Z spiders in Definition 4. Note that $m_1 + m_2 + k = n$. Correspondingly, the XZ normal form for the Steane code is drawn in Figure 2.4b.

In [55], Kissinger gave an algorithm to rewrite any phase-free ZX diagram into both the ZX and XZ normal forms. In Appendix A, we prove that it is sufficient to represent a CSS code encoder using either one of the forms.



(a) The Steane code encoder in the ZX normal form. (b) The Steane code encoder in the XZ normal form.

Figure 2.4: The XZ and ZX normal forms of the Steane code.

Chapter 3

The Graphical Construction of CSS Encoders

3.1 The ZX Normal Form for CSS Subsystem Codes

We generalize the ZX normal form for CSS stabilizer codes to CSS subsystem codes as follows.

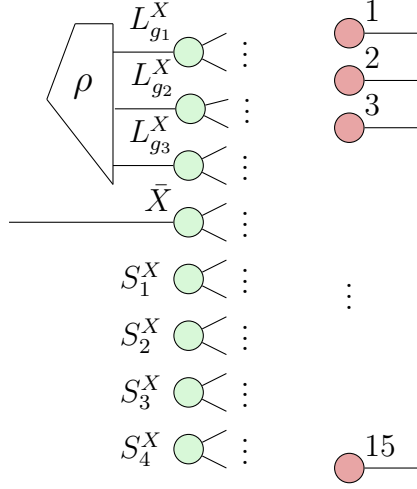
Definition 5. For an $[[n, k, r, d]]$ CSS subsystem code defined by $(\mathcal{S}, \mathcal{G})$, let $\{S_i^X; 1 \leq i \leq m\}$ be the X-type stabilizer generators, $\{L_{g_t}^X; 1 \leq t \leq r\}$ be the X-type gauge operators, and $\{\overline{X}_j; 1 \leq j \leq k\}$ be the logical X operators, $m + k + r < n$. Its ZX normal form can be found via the following steps:

- (a) For each physical qubit, introduce an X spider.
- (b) For each stabilizer generator S_i^X , logical operator \overline{X}_j and gauge operator $L_{g_t}^X$, introduce a Z spider and connect it to all X spiders where this operator has support.
- (c) Give each X spider an output wire.
- (d) For each Z spider representing \overline{X}_j , give it an input wire.
- (e) For all Z spiders representing $L_{g_t}^X$, attach to them a joint arbitrary input state (i.e., a density operator ρ).

Similar to CSS stabilizer codes, CSS subsystem codes also have an equivalent XZ normal form, which can be found by inverting the role of Z and X in the above procedure.

For $n > 3$, below we exemplify the ZX normal form for an $[[n, 1, 2, d]]$ CSS subsystem code with three X-type stabilizers generators $\{S_1^X, S_2^X, S_3^X\}$, two X-type gauge operators $\{L_{g_1}^X, L_{g_2}^X\}$, and one logical operator $\{\overline{X}\}$. For simplicity, we substitute wires connecting Z and X spiders by \frown . The detailed connectivities are omitted here, but they should be

clear following step (b) in Definition 5. This notation will be used in the remainder of this paper.



3.2 Pushing through the Encoder

For any $[[n, k, d]]$ CSS code, its encoder map E is of the form:

$$k \left\{ \begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \right\} \begin{array}{c} \boxed{E} \\ \vdots \\ \vdots \end{array} \left. \begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \right\} n.$$

Definition 6. Let \bar{X}_i and \bar{Z}_i be the X and Z operators acting on the i -th logical qubit. Let $\bar{\mathcal{X}}_i$ and $\bar{\mathcal{Z}}_i$ be the physical implementation of \bar{X}_i and \bar{Z}_i respectively. Diagrammatically, they can be represented as

$$\begin{array}{c} \boxed{\bar{\mathcal{X}}_1} \\ \vdots \\ \vdots \end{array} \begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \boxed{E} \begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} = \begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \boxed{E} \begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \boxed{\bar{\mathcal{X}}_1} \begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \quad \text{and} \quad \begin{array}{c} \boxed{\bar{\mathcal{Z}}_1} \\ \vdots \\ \vdots \end{array} \begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \boxed{E} \begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} = \begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \boxed{E} \begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \boxed{\bar{\mathcal{Z}}_1} \begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} .$$

In other words, pushing \bar{X}_i (or \bar{Z}_i) through E yields $\bar{\mathcal{X}}_i$ (or $\bar{\mathcal{Z}}_i$). Using ZX rewrite rules along with the ZX (or XZ) normal form, we can prove Lemma 2. Although this is a well-known fault-tolerant property of the CSS codes, this graphical proof reveals how logical Pauli operators are propagated through the encoder.

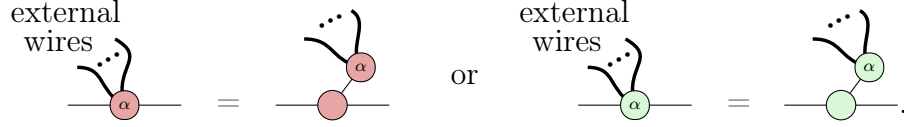
Lemma 2. For any CSS code, all \bar{X}_i and \bar{Z}_i are implementable by multiple single-qubit Pauli operators. In other words, all CSS codes have transversal \bar{X}_i and \bar{Z}_i .

Proof. Consider an arbitrary CSS code. Without loss of generality, represent its encoder E in the ZX normal form following Definition 4. Then proceed by applying the π -copy' rule on every \bar{X}_i (the X spider with a phase π on the left-hand side of the encoder E). \square

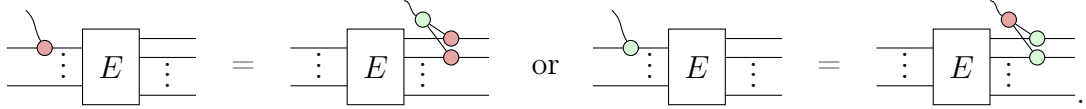
Beyond just X or Z spiders, one can push *any* logical ZX diagram through the encoder. Such pushing is bidirectional, and the left-to-right direction is interpreted as finding a physical implementation for a given logical operator.

Proposition 1. Let E be the encoder of a CSS code. For any ZX diagram L on the left-hand side of E , one can write down a corresponding ZX diagram P on the right-hand side of E , such that $EL = PE$. In other words, P is a valid physical implementation of L for that CSS code.

Proof. We proceed as follows. First, unfuse all spiders on the logical qubit wires of L , whenever they are not phase-free or have more than one external wire:



For each X (or Z) spider on the logical qubit wire, rewriting E to be in ZX (or XZ) normal form and applying the strong complementarity (sc) rule yields:



On the left-hand side, a phase-free X (or Z) spider acts on the i -th logical qubit; on the right-hand side, phase-free X (or Z) spiders act on all physical qubits wherever \overline{X}_i (or \overline{Z}_i) has support. Therefore, any type of L can be pushed through E , resulting in a diagram P which satisfies $EL = PE$. \square

In [39], it was proved that a physical implementation P of a logical operator L satisfies $L = E^\dagger P E$. This is implied by $EL = PE$ as $E^\dagger E = I$.

3.3 Examples

To illustrate Lemma 2 and proposition 1, we use the $[[4, 2, 2]]$ code for an example. This code is defined by the stabilizer group $\mathcal{S} = \langle X_1 X_2 X_3 X_4, Z_1 Z_2 Z_3 Z_4 \rangle$ and a set of logical operators \mathcal{L} :

$$\mathcal{L} = \{\overline{X}_1, \overline{Z}_1, \overline{X}_2, \overline{Z}_2\}, \quad \overline{X}_1 = X_1 X_2, \quad \overline{Z}_1 = Z_1 Z_3, \quad \overline{X}_2 = X_1 X_3, \quad \overline{Z}_2 = Z_1 Z_2.$$

Its ZX and XZ normal forms are shown in Figure 3.1. Figure 3.1a is the ZX normal form defined by the logical X operators and the X-type stabilizer generator. Figure 3.1b is the XZ normal form defined by the logical Z operators and the Z-type stabilizer generator.

In what follows, we use Examples 2 to 5 to articulate the proof of Proposition 1.

Example 2 (Implement a Logical XX Measurement). *The fundamental building block for lattice surgery is a multi-qubit Pauli measurement across two lattices. In Figure 3.3, we show that a non-destructive logical-qubit measurement in (i) can be implemented by a non-destructive physical-qubit measurement in (v).*

To start, substitute the $[[4, 2, 2]]$ encoder by Figure 3.1a, as shown in (ii). Then, consider the bottom lattice (i.e., the second code block) and the Z spider with a $k\pi$ phase as an exterior attachment to the X spider in the top lattice (i.e., the first code block). Applying the strong complementarity (sc) rule to the top lattice yields (iii), which is the partially fixed ZX diagram. After that, consider the top-fixed lattice as an attachment to the bottom lattice and apply the sc rule. This results in (iv), which is equivalently expressed in (v). This transformation agrees with the graphical derivation for the colour code lattice surgery [50].

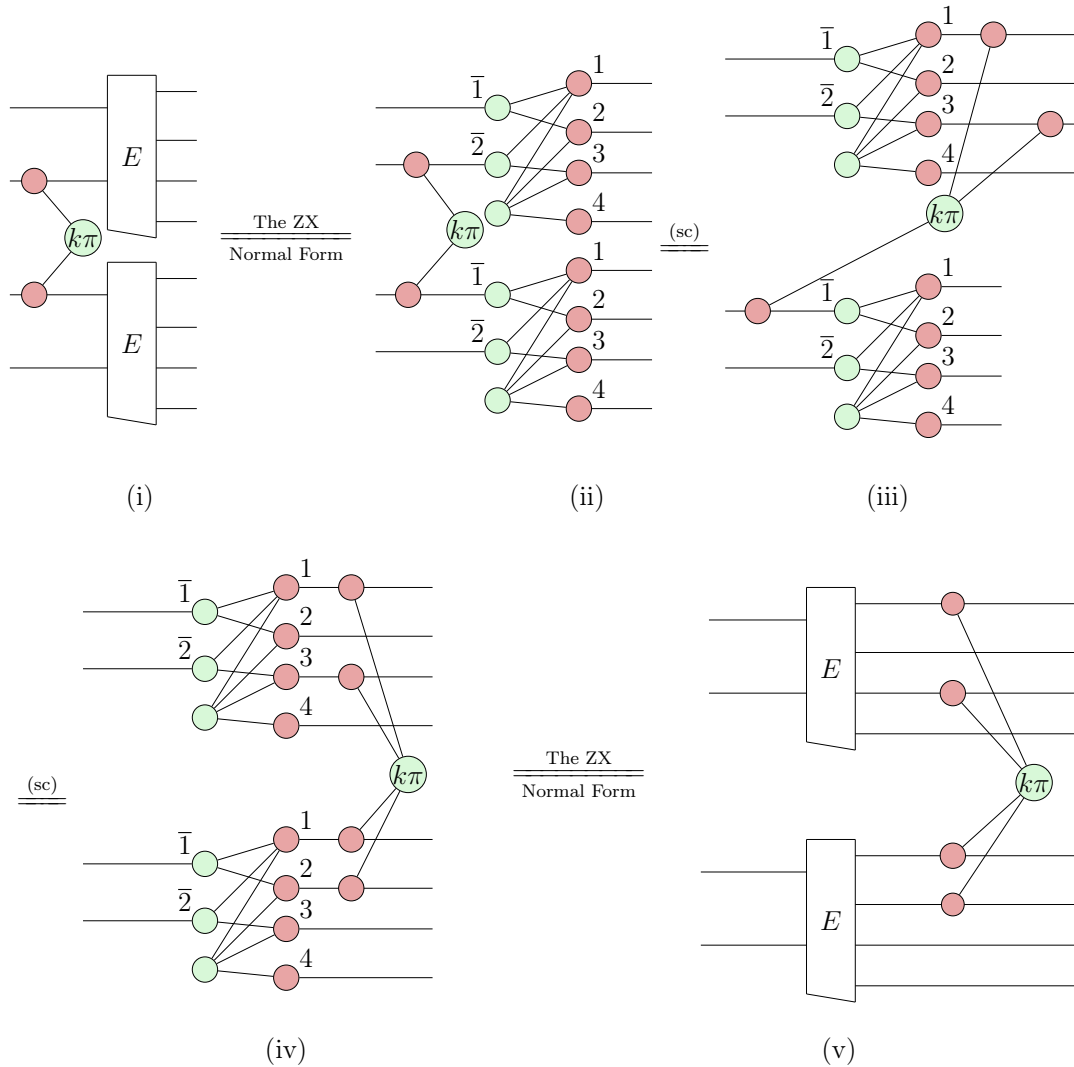


Figure 3.3: By pushing the logical XX measurement through the encoder, we show that a Pauli measurement of two logical blocks can be implemented by a Pauli measurement of multiple physical qubits.

Example 3 (Implement a Logical CNOT Gate). *To push a logical CNOT through the encoder, we proceed by case distinctions.*

Case 1: *When a CNOT acts on two logical qubits within one code block.*

In Figure 3.4, we push the CNOT through the encoder by applying Proposition 1. Equivalently, we find the physical implementation of a logical CNOT for the $[[4, 2, 2]]$ code.

Case 2: *When a CNOT acts on two logical qubits across two code blocks.*

In Figure 3.5, after applying a sequence of rewrite rules, a logical CNOT is pushed through the encoder. As a result, we find the physical implementation of a logical CNOT acting on two code blocks. Alternatively, in Figure 3.6, we apply Proposition 1 and derive the same result.

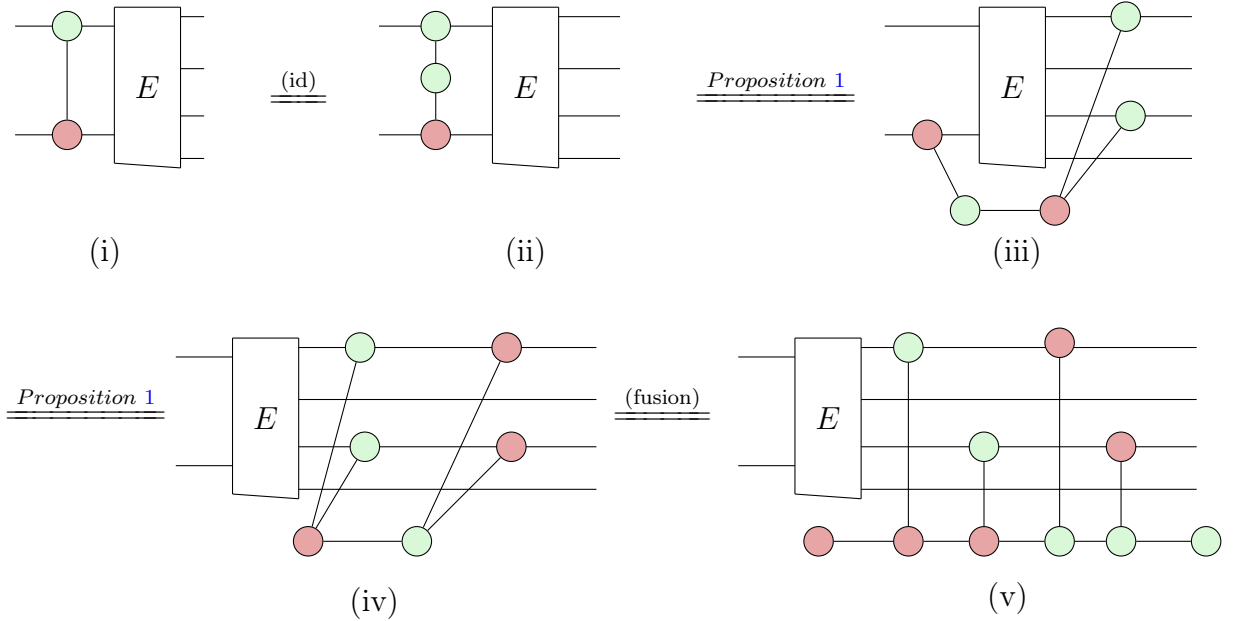


Figure 3.4: When a logical CNOT acts within one code block, push the CNOT through the encoder by applying Proposition 1. As a result, we find a non-transversal implementation of this logical CNOT gate, as shown in (v).

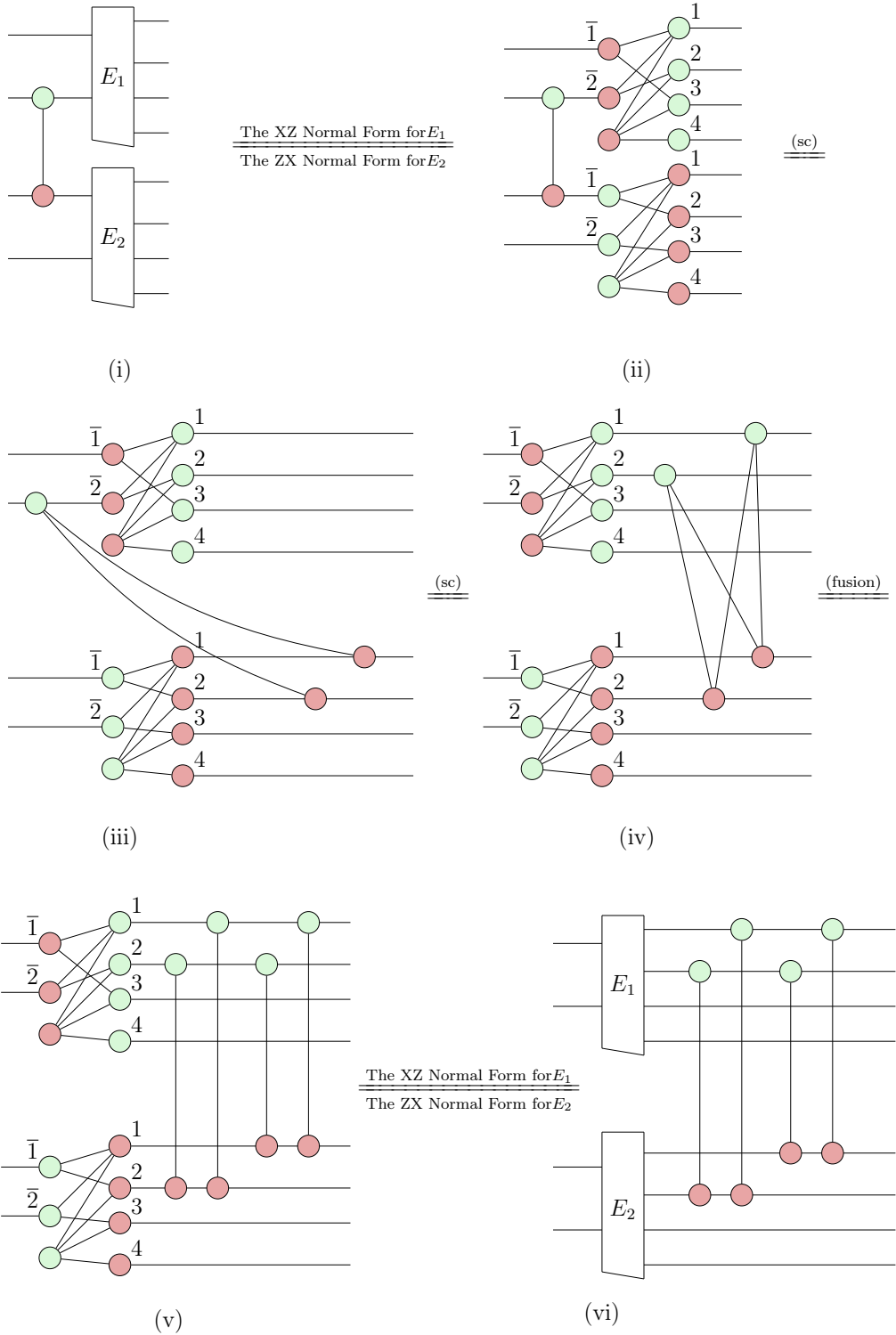


Figure 3.5: When a logical CNOT acts on two code blocks, push the CNOT through the encoder by applying a sequence of rewrite rules. As a result, we find a transversal implementation of this logical CNOT gate, as shown in (vi).

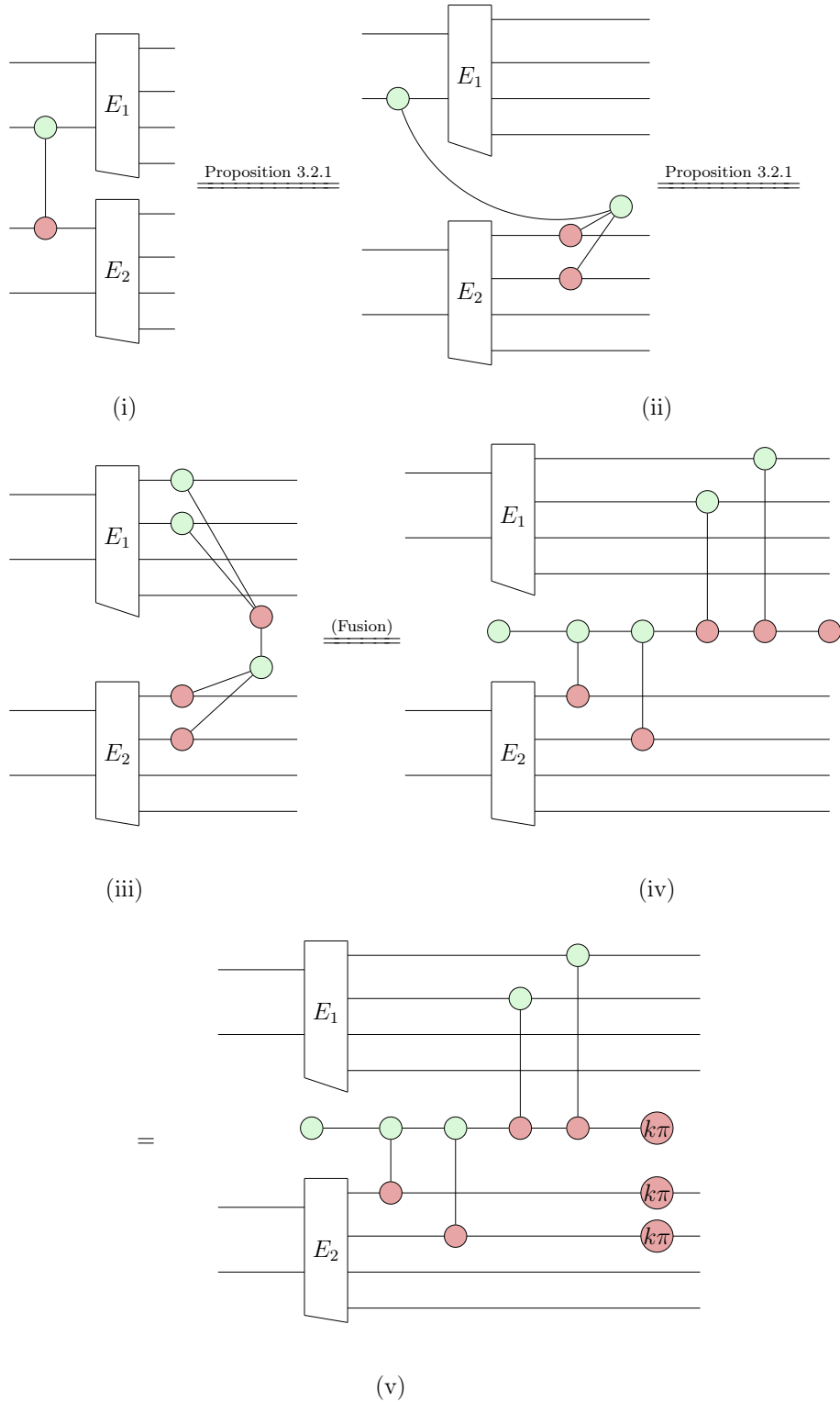


Figure 3.6: When a logical CNOT acts on two code blocks, push the CNOT through the encoder by applying Proposition 1. In (v), $k \in \mathbb{Z}_2$. We can interpret the physical implementation in terms of the following steps. First, prepare a logical ancilla in the $|+\rangle$ state. For each physical qubit where $\overline{X}_2 = X_1 X_3$ or $\overline{Z}_1 = Z_1 Z_3$ has support, apply a CNOT on this qubit and the ancilla. Next, measure the ancilla in the Pauli Z basis. Finally, if the measurement output is $k = 1$, apply a Pauli X correction on the physical qubits where $\overline{X}_2 = X_1 X_3$ has its support.

Example 4 (Implement a Logical T Gate). *In Figure 3.7, we push a logical T gate through the encoder by applying a sequence of rewrite rules. This helps visualize the techniques used in proving Proposition 1.*

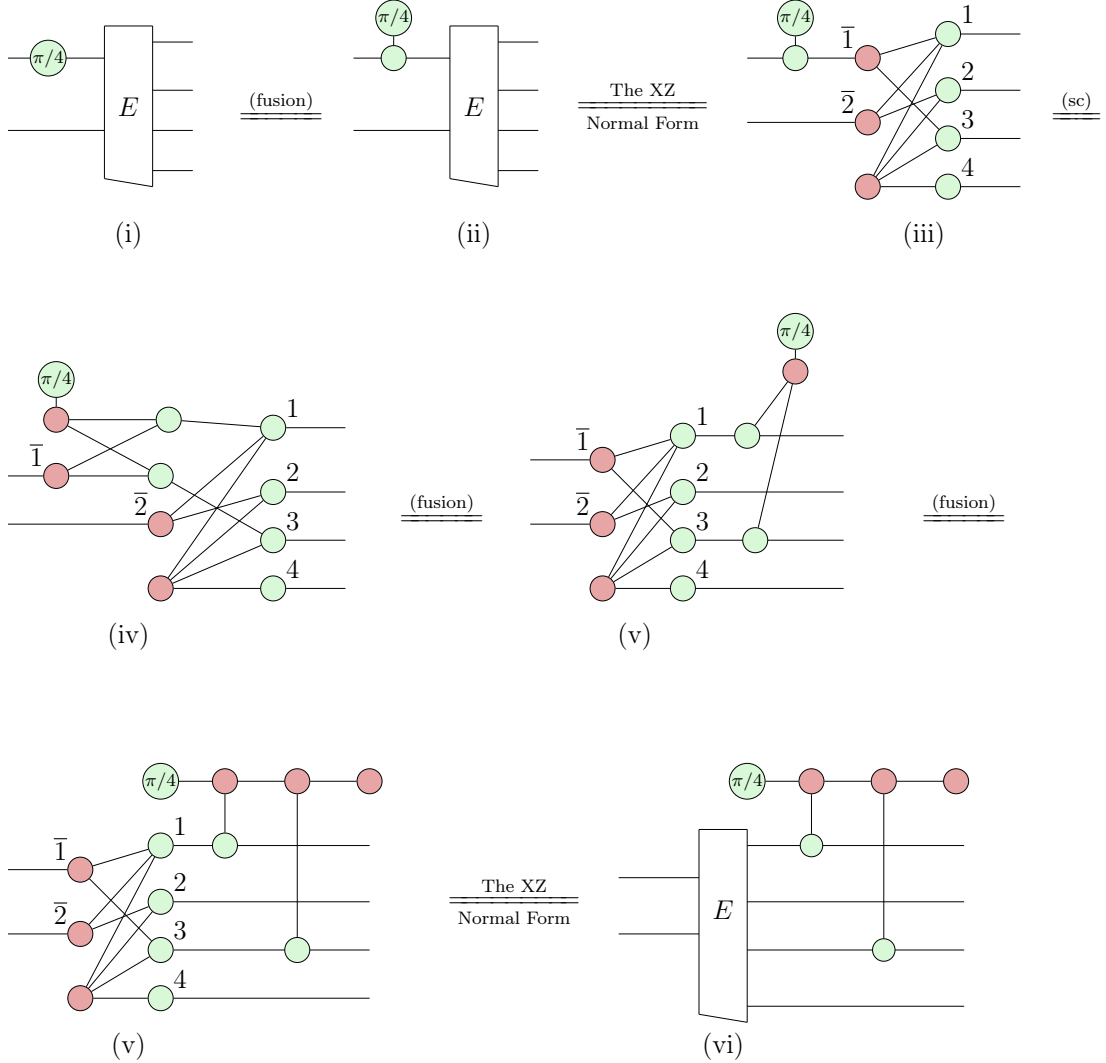


Figure 3.7: A logical T gate is pushed through the encoder by applying a sequence of rewrite rules. As a result, we find a non-transversal implementation of this logical T gate, as shown in (vi).

Example 5 (Implement a Logical Hadamard Gate). *In Figure 3.8, we show how to find a physical implementation of a logical Hadamard gate by applying Proposition 1.*

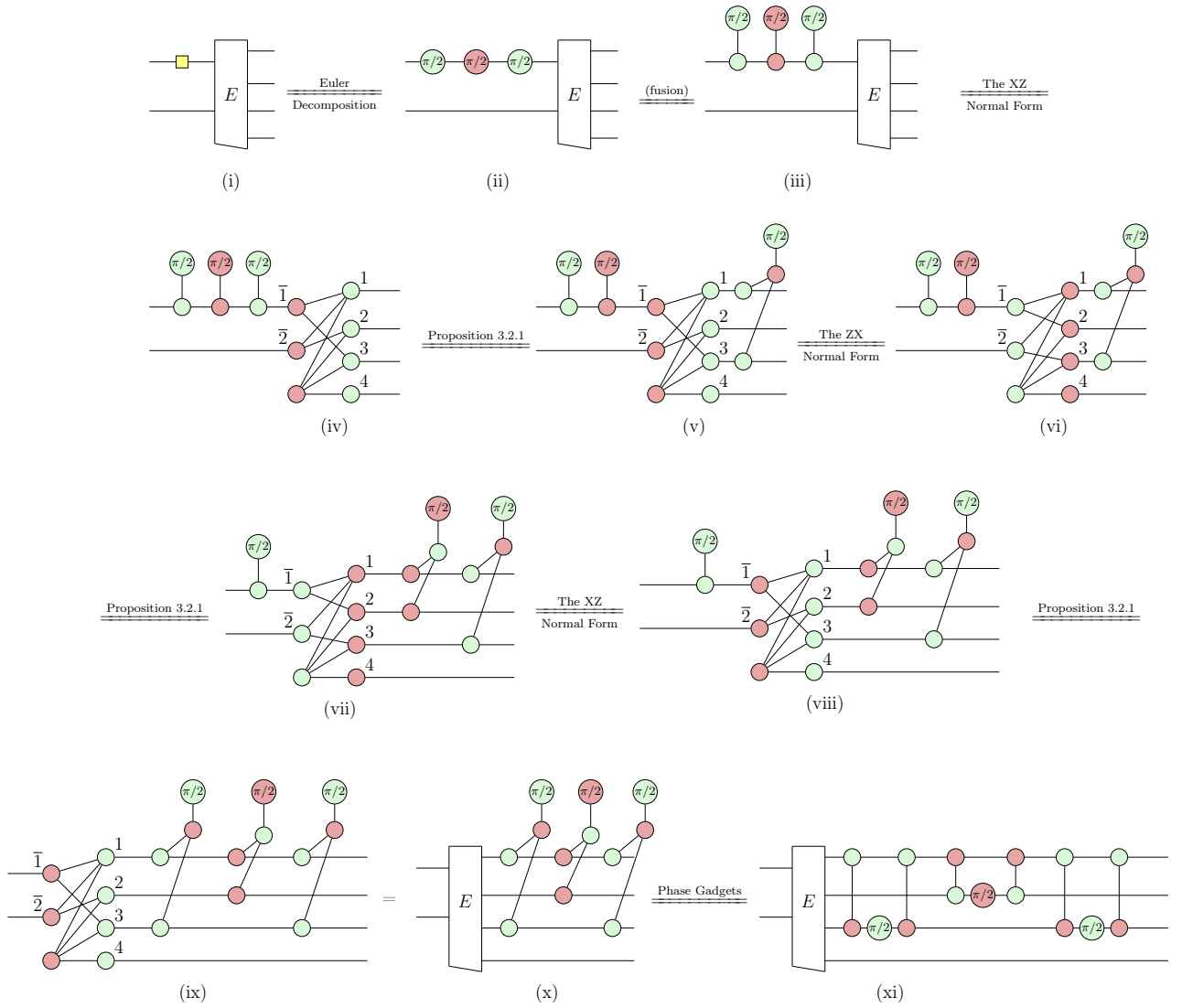


Figure 3.8: To push a logical Hadamard gate through the encoder, we first apply the Euler decomposition (ii). After unfusing logical spiders (iii), apply Proposition 1 three times and each time with a convenient normal form. As a result, we find a non-transversal implementation of this logical Hadamard gate, as shown in (xi).

Chapter 4

Graphical Morphing of CSS Codes

One way to transform CSS codes is known as *code morphing*. It provides a systematic framework to construct new codes from an existing code while preserving the number of logical qubits in the morphed code. Here, we present this procedure by rewriting the encoder diagram using the ZX calculus. We start by revisiting the code morphing definition in [92].

Definition 7. Let \mathcal{S} be a stabilizer group and \mathcal{C} be its joint $+1$ eigenspace. \mathcal{C} is called the parent code. Let Q denote the set of physical qubits of \mathcal{C} and $R \subseteq Q$. Then $\mathcal{S}(R)$ is a subgroup of \mathcal{S} generated by all stabilizers of \mathcal{S} that are fully supported on R . Let $\mathcal{C}(R)$ be the joint $+1$ eigenspace of $\mathcal{S}(R)$, and $\mathcal{C}(R)$ is called the child code. Given the parent code encoder $E_{\mathcal{C}}$, concatenate it with the inverse of the child code encoder $E_{\mathcal{C}(R)}^\dagger$. This gives the morphed code $\mathcal{C}_{\setminus R}$.

Definition 8. Let M be a stabilizer generator of a CSS code. Let $\text{supp}(M)$ be the set of physical qubits where M acts non-trivially. For brevity, we call $\text{supp}(M)$ the support of M . There are three types of qubit coverage of R concerning $\text{supp}(M)$.

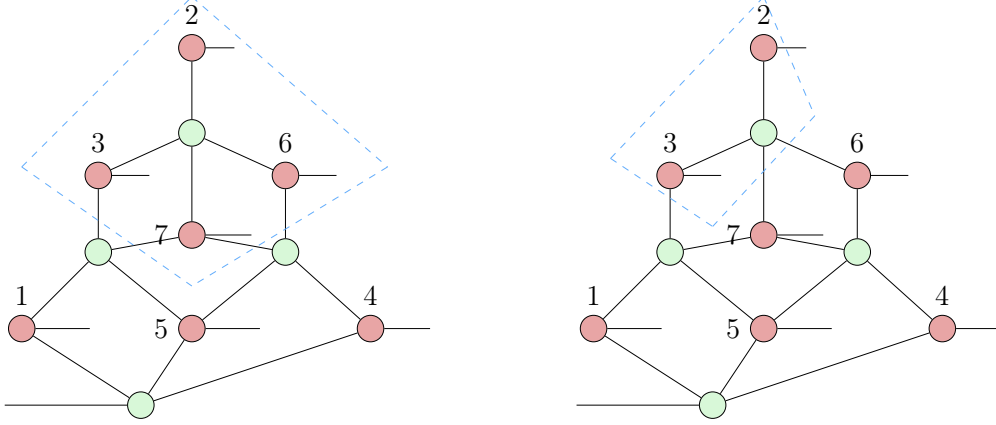
- When $|\text{supp}(M) \cap R| = |\text{supp}(M)|$, M is fully-supported on R .
- When $0 < |\text{supp}(M) \cap R| < |\text{supp}(M)|$, M is partially-supported on R .
- When $|\text{supp}(M) \cap R| = 0$, M is not supported on R .

In Figure 4.1 we use the $[[7, 1, 3]]$ Steane code to illustrate different types of qubit coverage. Without loss of generality, consider its ZX normal form. Its X-type stabilizer generators and their respective supports are as follows.

$$\begin{aligned} S_1^X &= X_1 X_3 X_5 X_7, & \text{supp}(S_1^X) &= \{1, 3, 5, 7\}, \\ S_2^X &= X_2 X_3 X_6 X_7, & \text{supp}(S_2^X) &= \{2, 3, 6, 7\}, \\ S_3^X &= X_4 X_5 X_6 X_7, & \text{supp}(S_3^X) &= \{4, 5, 6, 7\}. \end{aligned}$$

In Figure 4.1a, take $R_1 = \{2, 3, 6, 7\} \subset Q$. Since $|\text{supp}(S_1^X) \cap R_1| = |\{3, 7\}| = 2 < 4$, $|\text{supp}(S_3^X) \cap R_1| = |\{6, 7\}| = 2 < 4$, S_1^X and S_3^X are partially supported on R_1 . Since $|\text{supp}(S_2^X) \cap R_1| = |\{2, 3, 6, 7\}| = 4$, S_2^X is fully supported on R_1 .

In Figure 4.1b, take $R_2 = \{2, 3\} \subset Q$. Since $|\text{supp}(S_1^X) \cap R_2| = |\{3\}| = 1 < 4$, $|\text{supp}(S_2^X) \cap R_2| = |\{2, 3\}| = 2 < 4$, S_1^X and S_3^X are partially supported on R_2 . Since $|\text{supp}(S_3^X) \cap R_2| = |\emptyset| = 0$, S_3^X is not supported on R_2 .



(a) $R_1 = \{2, 3, 6, 7\}$ corresponds to the 4 X spiders in the blue dashed box. (b) $R_2 = \{2, 3\}$ corresponds to the 2 X spiders in the blue dashed box.

Figure 4.1: Given the ZX normal form of the Steane code, $Q = \{1, 2, 3, 4, 5, 6, 7\}$. Different choices of $R \subset Q$ provide different coverage for an X-type stabilizer generator.

Figure 4.2 provides two equivalent interpretations for the code morphing process. In Figure 4.2a, Definition 7 is depicted by the circuit diagram. Since $E_{C(R)}$ is an isometry, $E_{C(R)}^\dagger E_{C(R)} = I$. By construction, the equation shown in Figure 4.2a holds [92]. Moreover, the parameters of $\mathcal{C} = \llbracket n, k, d \rrbracket$, $\mathcal{C}(R) = \llbracket n_1, k_1, d_1 \rrbracket$, and $\mathcal{C}_{\setminus R} = \llbracket n_2, k_2, d_2 \rrbracket$ are characterized below. Let m, m_1, m_2 be the number of stabilizer generators for \mathcal{C} , $\mathcal{C}(R)$, and $\mathcal{C}_{\setminus R}$ respectively. Then

$$n_2 = n - n_1 + k_1, \quad k_2 = k, \quad m_2 = (n - k) - (n_1 - k_1) = m - m_1, \quad d_1, d_2 \in \mathbb{N}.$$

Figure 4.2b provides a concrete example of applying Definition 7 to the $\llbracket 7, 1, 3 \rrbracket$ Steane code, where $S = \{1, 2, 3, 4, 5, 6, 7\}$ and $R = \{2, 3, 6, 7\}$. As a result, the $\llbracket 5, 1, 2 \rrbracket$ code is morphed from the parent code along with the $\llbracket 4, 2, 2 \rrbracket$ child code. This morphed code inherits a fault-tolerant implementation of the Clifford group from the $\llbracket 7, 1, 3 \rrbracket$ code, which has a transversal implementation of the logical Clifford operators. This morphing process is represented in the ZX diagram by cutting the edges labelled by $\bar{1}$ and $\bar{2}$ adjacent to the X spider. This is equivalent to concatenating the ZX diagram of $E_{\llbracket 4, 2, 2 \rrbracket}^\dagger$ in Figure 4.2a.

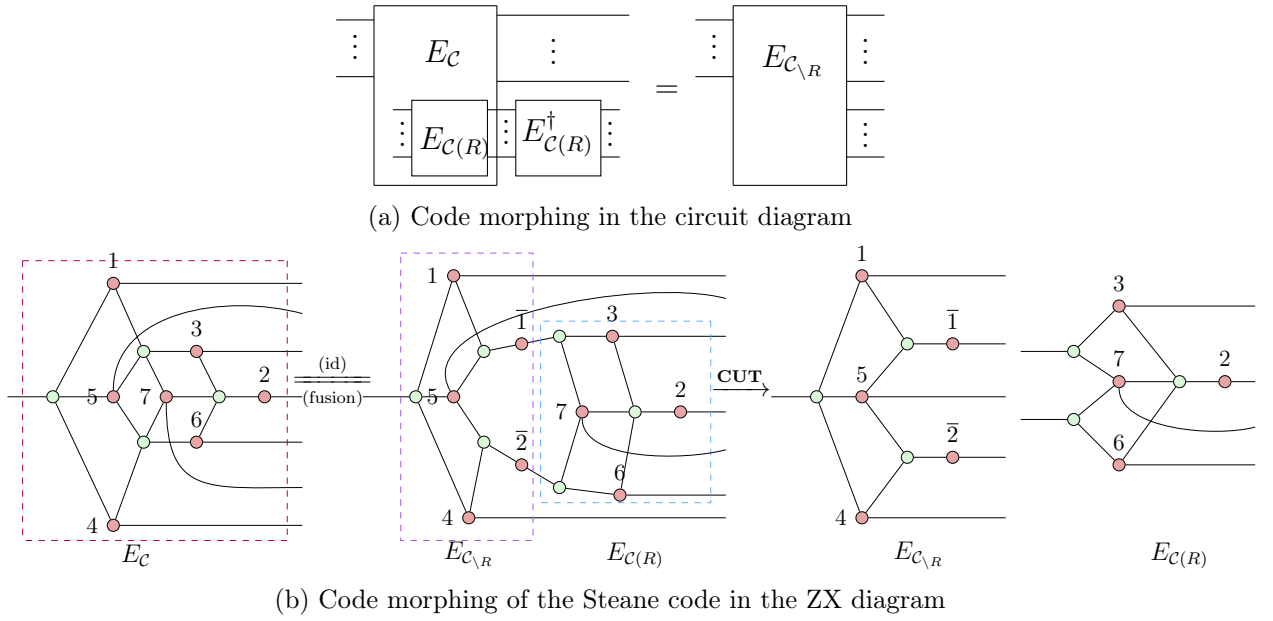


Figure 4.2: Code morphing can be visualized using both circuit and ZX diagrams. In Figure 4.2a, code morphing is viewed as a concatenation of the parent code encoder E_C and the inverse of the child code encoder $E_{C(R)}^\dagger$. In Figure 4.2b, the encoder E_C of the Steane code is represented in the ZX normal form. As described in Proc. 1, by applying ZX rules (id) and (fusion) in Figure 2.2, we can perform code morphing by bipartitioning it into the encoder $E_{C \setminus R}$ of the morphed code $\mathcal{C}_{\setminus R} = \llbracket 5, 1, 2 \rrbracket$, and the encoder $E_{C(R)}$ of the child code $\mathcal{C}(R) = \llbracket 4, 2, 2 \rrbracket$.

Next, we generalize the notion of code morphing and show how ZX calculus could be used to study these relations between the encoders of different CSS codes. More precisely, we provide an algorithm to morph a new CSS code from an existing CSS code.

Procedure 1. *Given a parent code \mathcal{C} and a child code $\mathcal{C}(R)$ satisfying Definition 7, construct the encoder of \mathcal{C} in the ZX normal form. Then the code morphing proceeds as follows:*

- (a) *Unfuse every Z spider which is supported on c qubits within R and f qubits outside R , $c \neq 0$, $f \neq 0$.*
- (b) *Add an identity X spider between each pair of Z spiders being unfused in step (a).*
- (c) *Cut the edge between every identity X spider and the Z spiders supported on the f qubits in R .*

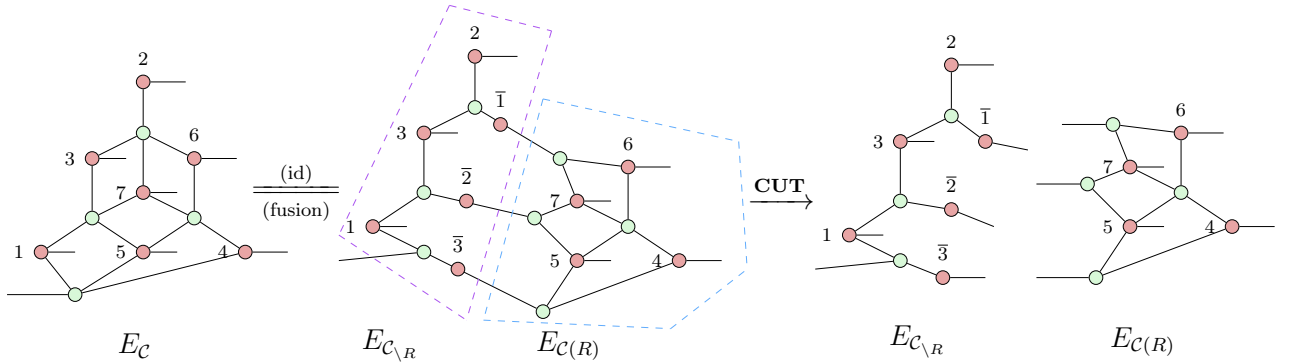
It follows that the subdiagram containing R corresponds to the ZX normal form of $E_{C(R)}$. It has the same number of X spiders as R , so $n_1 = |R|$. Suppose that there are h Z spiders being unfused. Then h must be bounded by the number of Z spiders in the ZX normal form of E_C . As each spider unfusion introduces a logical qubit to $\mathcal{C}(R)$, $k_1 = h$. On the other hand, the complement subdiagram contains $n - n_1 + k_1$ X spiders as each edge cut introduces a new X spider into the complement subdiagram. It also contains k

logical qubits as the input edges in the ZX normal form of E_C are invariant throughout the spider-unfusing and edge-cutting process. This gives the ZX normal form for the encoder of the morphed code $\mathcal{C}_{\setminus R} = \llbracket n_2, k_2, d_2 \rrbracket$, where $n_2 = n - n_1 + k_1$, $k_2 = k$, $d_2 \in \mathbb{N}$. As a result, the ZX normal form of E_C is decomposed into the ZX normal forms of $E_{C(R)}$ and $E_{\mathcal{C}_{\setminus R}}$ respectively.

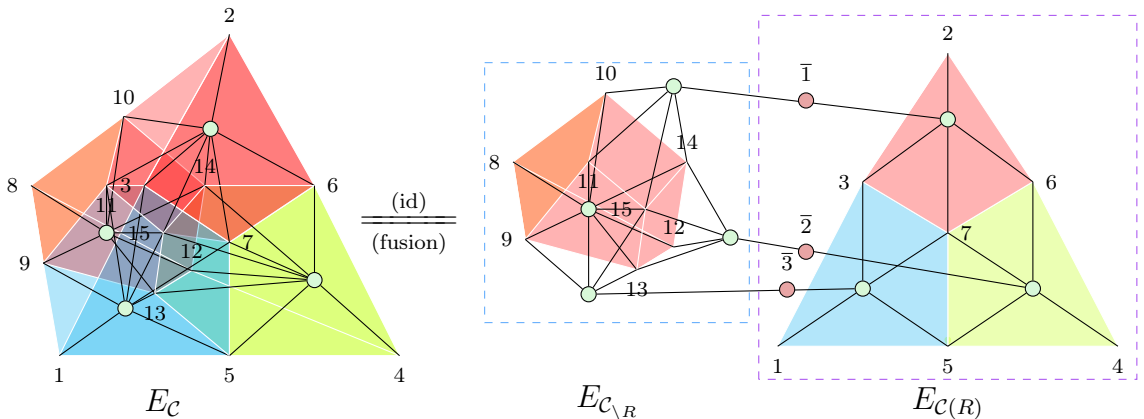
As the XZ and ZX normal forms are equivalent for CSS codes, Proc. 1 can be carried out for the XZ normal form by inverting the roles of Z and X at each step.

Here, we exemplify the application of Proc. 1 by morphing two simple CSS codes. Unlike Figure 4.2b, Example 6 chooses a different subset of qubits, $R = \{4, 5, 6, 7\}$, to obtain the $\llbracket 6, 1, 1 \rrbracket$ morphed code. In Example 7, we visualize the $\llbracket 10, 1, 2 \rrbracket$ code morphing from the $\llbracket 15, 1, 3 \rrbracket$ quantum Reed-Muller code. The $\llbracket 10, 1, 2 \rrbracket$ code is interesting because it inherits a fault-tolerant implementation of the logical T gate from its parent code, which has a transversal implementation of the logical T gate.

Example 6. Let the parent code \mathcal{C} be the Steane code and the child code be $C(R) = \llbracket 4, 3, 1 \rrbracket$. By Proc. 1, we obtain the morphed code $\mathcal{C}_{\setminus R} = \llbracket 6, 1, 1 \rrbracket$. Note that for $C(R)$, there is one X -type stabilizer generator and no Z -type stabilizer generator. This means that $C(R)$ cannot detect a single-qubit X error, so it has a distance of 1. In $\mathcal{C}_{\setminus R}$, the physical qubit labelled $\bar{3}$ is not protected by any X -type stabilizer. Therefore, $\mathcal{C}_{\setminus R}$ is of distance 1.



Example 7. Let the parent code \mathcal{C} be the quantum Reed-Muller and the child code be $C(R) = \llbracket 8, 3, 2 \rrbracket$. By Proc. 1, we obtain the morphed code $\mathcal{C}_{\setminus R} = \llbracket 10, 1, 2 \rrbracket$. For brevity, the X spiders representing physical qubits and the logical qubit wires inputting to the Z spiders are omitted.



Chapter 5

Graphical Code Switching of CSS Codes

Another way to transform CSS codes is known as *code switching*. It is a widely studied technique in quantum error correction. Codes with complementary fault-tolerant gate sets are switched between each other to realize a universal set of logical operations. As a case study, we focus on the code switching protocol between the Steane code and the quantum Reed-Muller code [3, 74, 77]. Since this process is bidirectional, the reasoning for one direction can be simply adjusted for the opposite direction. Recall in Lemma 1, we showed that the extended Steane code is equivalent to the Steane code up to some auxiliary state. In what follows, we focus on the *backward switching* from the quantum Reed-Muller code to the extended Steane code.

Using the ZX calculus, we provide a graphical interpretation for the backward code switching. More precisely, it is visualized as gauge-fixing the $[[15, 1, 3, 3]]$ subsystem code, followed by a sequence of syndrome-determined recovery operations.

We first characterize the relations between the quantum Reed-Muller code, the extended Steane code, and the $[[15, 1, 3, 3]]$ subsystem code. For brevity, we denote these codes as \mathcal{C}_{qrm} , \mathcal{C}_{ex} and \mathcal{C}_{sub} , and their respective encoders as E_{qrm} , E_{ex} , and E_{sub} .

Lemma 3. *When the three gauge qubits are in the $|\overline{+++}\rangle$ state, \mathcal{C}_{sub} is equal to \mathcal{C}_{ex} , as shown in Figure 5.1.*

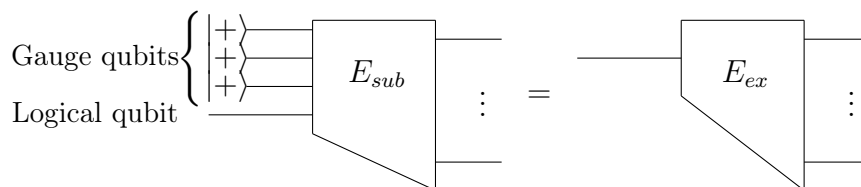
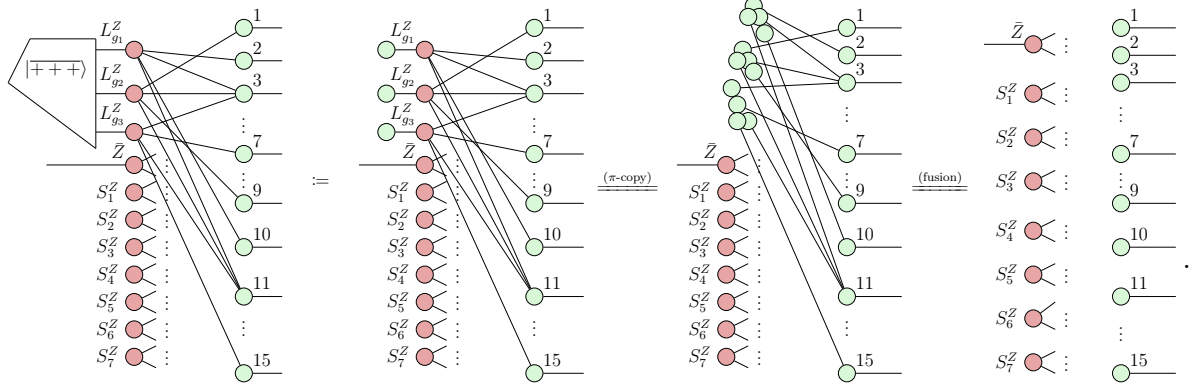


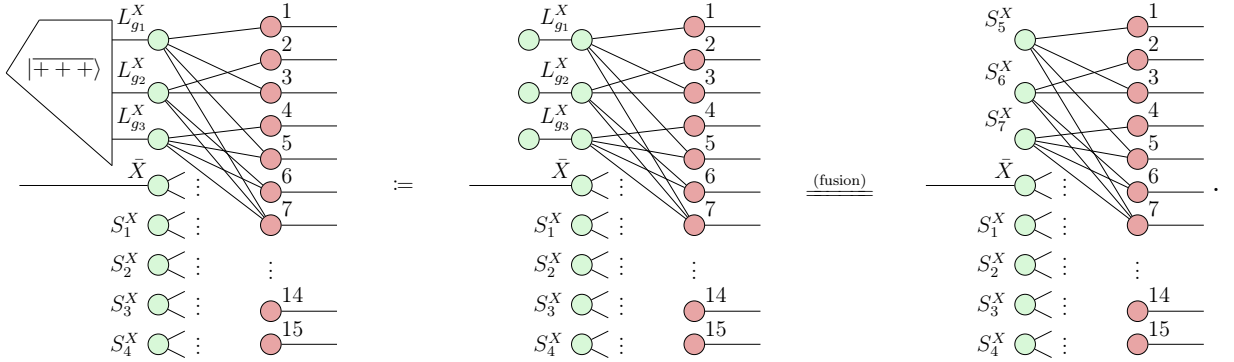
Figure 5.1: \mathcal{C}_{sub} is equivalent to \mathcal{C}_{ex} up to a fixed state of gauge qubits.

Proof. According to Definition 3, represent E_{sub} in the XZ normal form. With a sequence of rewrite rules, we obtain exactly the XZ normal form for E_{ex} which captures both the

Z-type stabilizer generators S_i^Z and the logical Z operators $L_{g_j}^Z$, $1 \leq i \leq 4$, $1 \leq j \leq 3$.



Alternatively, if one chooses to represent E_{sub} in the ZX normal form, the proof proceeds by applying the (fusion) rule to the Z spiders and identifying the gauge operators $L_{g_1}^X, L_{g_2}^X, L_{g_3}^X$ of \mathcal{C}_{sub} as the stabilizers S_5^X, S_6^X, S_7^X of \mathcal{C}_{ex} , respectively:



□

Corollary 2. When the three gauge qubits are in the $|\overline{000}\rangle$ state, \mathcal{C}_{sub} is equal to \mathcal{C}_{qrm} .

In [3, 74], code switching is described as a *gauge fixing* process. Further afield, [94] provides a generic recipe to gauge-fix a CSS subsystem code. Here, we generalize Lemma 3 and describe how to gauge-fix \mathcal{C}_{sub} to \mathcal{C}_{ex} using the ZX calculus.

Proposition 3. Gauge-fixing \mathcal{C}_{sub} in the following steps results in \mathcal{C}_{ex} , as shown in Figure 5.2.

- Measure three X-type gauge operators $L_{g_i}^X$ and obtain the corresponding outcomes $k_1, k_2, k_3 \in \mathbb{Z}_2$.
- When $k_i = 1$, the gauge qubit i has collapsed to the wrong state $|\bar{-}\rangle$. Apply the Z-type recovery operation $L_{g_i}^Z$.

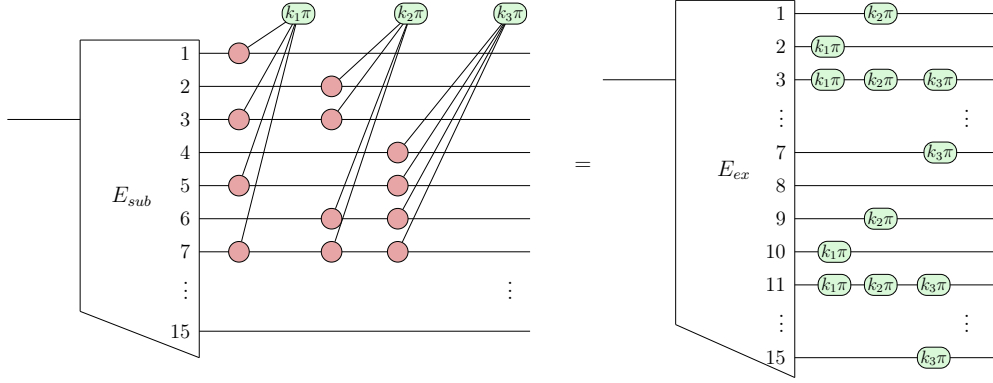


Figure 5.2: Gauge-fixing \mathcal{C}_{sub} to \mathcal{C}_{ex} in the circuit diagram.

Proof. In Figure 5.3, we proceed by applying a sequence of ZX rewrite rules. By Definition 5, construct the ZX normal form of E_{sub} in the blue dashed box of (i). Then the three gauge operators $L_{g_i}^X$ are measured in step (a). The subsequent equalities follow from Figures 2.2 and 2.3. Next, we observe that the purple dashed box in (iii) is exactly the encoder of the $[[15, 4, 3]]$ stabilizer code. By Lemma 3.2 in [55], it can be equivalently expressed in the XZ normal form, as in (iv). By Proposition 1, pushing each Z spider with the phase $k_i\pi$ across $E_{[[15,4,3]]}$ results in (v). In step (b), Pauli Z operators are applied based upon the measurement outcome k_i , which corresponds to the recovery operations in the red dashed box of (v). After that, the gauge qubits of \mathcal{C}_{sub} are set to the $|+++ \rangle$ state. By Lemma 3, we obtain the XZ normal form for E_{ex} , as shown in the orange dashed box of (vi). Therefore, the equation in Figure 5.2 holds. \square

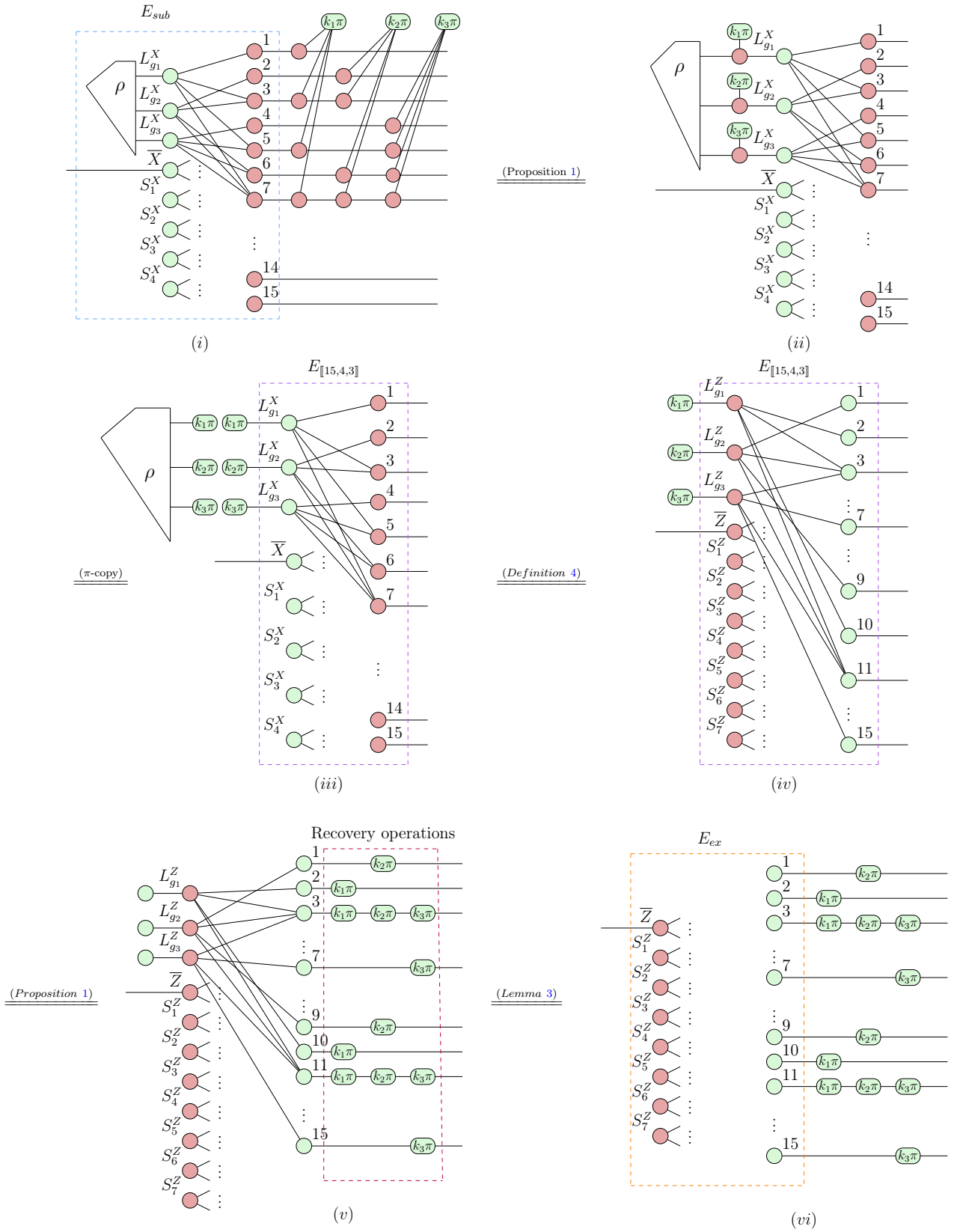


Figure 5.3: The graphical proof for Proposition 3.

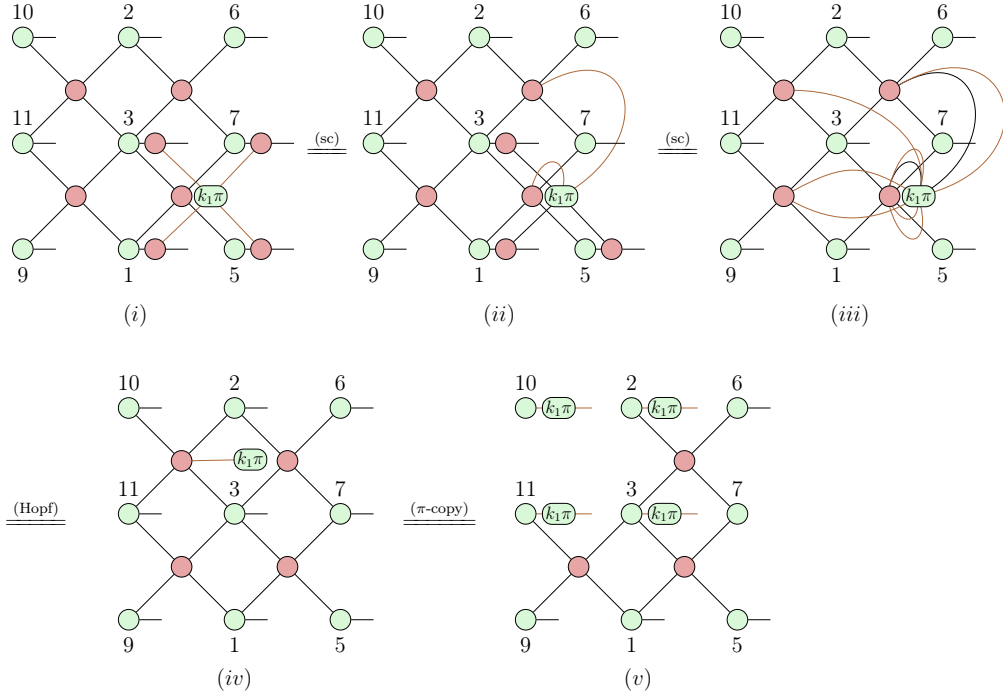


Figure 5.4: The switching from \mathcal{C}_{qrm} to \mathcal{C}_{ex} provides an alternative interpretation of Proposition 3. After measuring $L_{g_1}^X$, $L_{g_1}^Z$ is removed from the stabilizer group \mathcal{S}_{qrm} and the recovery operation is performed based on the measurement syndrome. Note that unrelated X and Z spiders are omitted from the ZX diagrams.

We sum up by explaining how to obtain \mathcal{C}_{ex} and \mathcal{C}_{qrm} by gauge-fixing \mathcal{C}_{sub} . In Proposition 3, we showed that measuring the X-type gauge operators $L_{g_i}^X$ followed by the Z-type recovery operations $L_{g_i}^Z$ is equivalent to adding $L_{g_i}^X$ to the stabilizer group \mathcal{S}_{sub} . This results in the formation of \mathcal{C}_{ex} . Analogously, measuring the Z-type gauge operators $L_{g_i}^Z$ followed by the X-type recovery operations $L_{g_i}^X$ is equivalent to adding $L_{g_i}^Z$ to \mathcal{S}_{sub} . Thus, we obtain \mathcal{C}_{qrm} .

Alternatively, gauge-fixing \mathcal{C}_{sub} can be viewed as a way of switching between \mathcal{C}_{ex} and \mathcal{C}_{qrm} [3, 77]. As an example, in Figure 5.4, we visualize the measurement of $L_{g_1}^X := X_1 X_3 X_5 X_7$ in order to switch from \mathcal{C}_{qrm} to \mathcal{C}_{ex} . The effect of measuring other X-type gauge operators can be reasoned analogously.

By Definition 5, construct the XZ normal form of E_{qrm} in (i). Then measure $L_{g_1}^X$ and apply a sequence of rewrite rules to the ZX diagram. In (v), the stabilizer $L_{g_1}^Z := Z_2 Z_3 Z_{10} Z_{11}$ is removed from the stabilizer group \mathcal{S}_{qrm} . Meanwhile, the recovery operation can be read off from the graphical derivation: $(Z_2 Z_3 Z_{10} Z_{11})^{k_1} = (L_{g_1}^Z)^{k_1}$, $k_1 \in \mathbb{Z}_2$.

Overall, ZX visualization provides a deeper understanding of the gauge fixing and code switching protocols. On top of revealing the relations between different CSS codes' encoders, it provides a simple yet rigorous test for various fault-tolerant protocols. Beyond this, it will serve as an intuitive guiding principle for the implementation of various logical operations.

Chapter 6

Conclusion

In this thesis, we generalize the notions in [55] and describe a normal form for CSS subsystem codes. Built upon the equivalence between CSS codes and the phase-free ZX diagrams, we provide a bidirectional rewrite rule to establish a correspondence between a logical ZX diagram and its physical implementation. With these tools in place, we provide a graphical representation of two code transformation techniques: code morphing, a procedure that transforms a code through unfusing spiders for the stabilizer generators, and gauge fixing, where different stabilizer codes can be obtained from a common subsystem code. These explicit graphical derivations show how the ZX calculus and graphical encoder maps relate several equivalent perspectives on these code transforming operations, allowing potential utilities of ZX to simplify fault-tolerant protocols and verify their correctness.

Looking ahead, many questions remain. It is still not clear how to present the general code deformation of CSS codes using phase-free ZX diagrams. Besides, understanding code concatenation through the lens of ZX calculus may help derive new and better codes. In addition, it would be interesting to look at other code modification techniques derived from the classical coding theory [71].

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Appendix A

The Complementary Proof

A.1 The ZX and XZ Normal Forms are Equivalent for a CSS Code

An $[[n, k, d]]$ CSS code \mathcal{C} is generated by orthogonal subspaces $V = \text{Span}\{v_1, \dots, v_{m_1}\}$ and $W = \text{Span}\{w_1, \dots, w_{m_2}\}$. $V, W \subset \mathbb{F}_2^n$, $m_1 = \dim V$ and $m_2 = \dim W$. m_1 and m_2 denote the number of independent X-type and Z-type stabilizer generators respectively. Then, the stabilizer generators of \mathcal{C} can be expressed as

$$S_i^X = \bigotimes_{t=1}^n X^{(v_i)_t}, \quad S_j^Z = \bigotimes_{t=1}^n Z^{(w_j)_t}.$$

Let \mathcal{S} be the stabilizer group of \mathcal{C} . Then

$$\mathcal{S} = \left\langle S_i^X, S_j^Z; 1 \leq i \leq m_1, 1 \leq j \leq m_2 \right\rangle.$$

Let E be the encoder of \mathcal{C} . Since E is an isometry from the k logical qubit space to the n physical qubit space, $E^\dagger E = I_k$ and $k = n - m_1 - m_2$ [46]. When a CSS code is not maximal, $m_1 + m_2 < n$. Then $k > 0$ and its logical operators can be expressed as

$$\bar{X}_i = \bigotimes_{t=1}^n X^{(v_i)_t}, \quad m_1 \leq i \leq m_1 + k$$

$$\bar{Z}_j = \bigotimes_{t=1}^n Z^{(w_j)_t}, \quad m_2 \leq j \leq m_2 + k$$

When a CSS code is *maximal*, \mathcal{S} is maximal and $V \oplus W = \mathbb{F}_2^n$. Thus $m_1 + m_2 = n$. $k = 0$ means that there is no degree of freedom for the encoded logical information. Therefore, the maximal CSS code is uniquely determined by \mathcal{S} . More precisely, it is the joint +1 eigenstate of the n independent stabilizer generators.

In Appendix A.1.1, we visualize a stabilizer generator of a CSS code using the ZX diagrams. In Appendix A.1.2, we explain the map-duality of a ZX diagram. This allows us to move spiders around and bend wires. In Appendix A.1.3, we leverage this property and prove Proposition 4, which states that it is sufficient to represent a CSS code using one of its ZX and XZ normal forms.

A.1.1 Represent a Stabilizer Generator Using the ZX Diagrams

In [55], a pictorial way was introduced to represent non-destructive Pauli measurements.

$$\mathcal{M}_{X\dots X} = \left\{ \prod_{X\dots X}^k := \frac{1}{2}(I + (-1)^k X \otimes \dots \otimes X) \right\}_{k=0,1}$$

$$\mathcal{M}_{Z\dots Z} = \left\{ \prod_{Z\dots Z}^k := \frac{1}{2}(I + (-1)^k Z \otimes \dots \otimes Z) \right\}_{k=0,1}$$

Definition 9. When $k = 0$, we obtain a phase-free version of the diagrams in Figure 2.3. They represent the X- and Z-type stabilizer generators, which are the projections onto the +1 eigenspace of a Pauli operator.

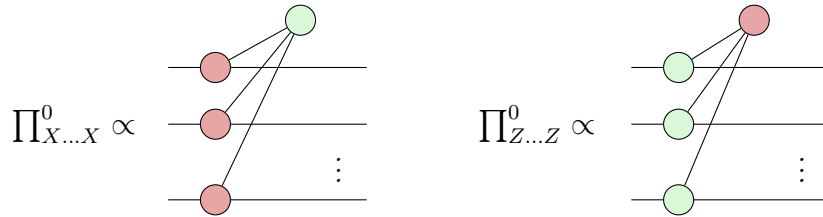


Figure A.1 use four examples to illustrate this notion. We can read off a Pauli projection from each ZX diagram. In Figure A.1a, since the X spiders are supported on the first two qubits, Pauli X acts on them and we get $I + XXI$. In Figure A.1b, since the X spiders are supported on all three qubits, we get $I + XXX$. Similarly, in Figures A.1c and A.1d, Pauli Z acts on qubits where Z spiders are supported.

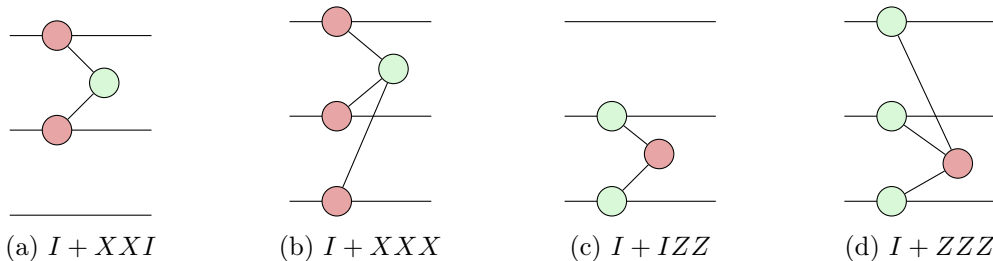


Figure A.1: Up to a scalar, each projection in $\{I + XXI, I + XXX, I + IZZ, I + ZZZ\}$ is represented by Figures A.1a to A.1d respectively. Here, I is short for $I^{\otimes 3}$.

A.1.2 The Map-State Duality of a ZX Diagram

Next, we introduce wires that are commonly used in a ZX diagram. In Figure A.2, a single wire corresponds to a one-qubit identity operator. A crossing wire corresponds to a SWAP operation. Wires in the shape of a cup or cap allow us to “bend” inputs around to become outputs and vice-versa. This corresponds to performing the partial transpose in the computational basis.

$$\text{—————} := \sum_i |i\rangle\langle i| \quad \text{X} := \sum_{ij} |ij\rangle\langle ji| \quad \left(\text{C} := \sum_i |ii\rangle \right) := \sum_i \langle ii|$$

Figure A.2: In addition to spiders, a ZX diagram could contain identity wires, swaps, cups, and caps [55].

Cups and caps help establish a bijection between a linear map $E : \mathbb{C}_2^{\otimes k} \rightarrow \mathbb{C}_2^{\otimes n}$ and the state $|E\rangle \in \mathbb{C}_2^{\otimes(k+n)}$, as shown in Figure A.3. This property is known as the *map-state duality*. It allows us to deform a ZX diagram arbitrarily by moving spiders around, bending, and unbending the wires. So long as the order of the diagram’s inputs and outputs is preserved, the deformed ZX diagram can be recovered to represent the same matrix [91].

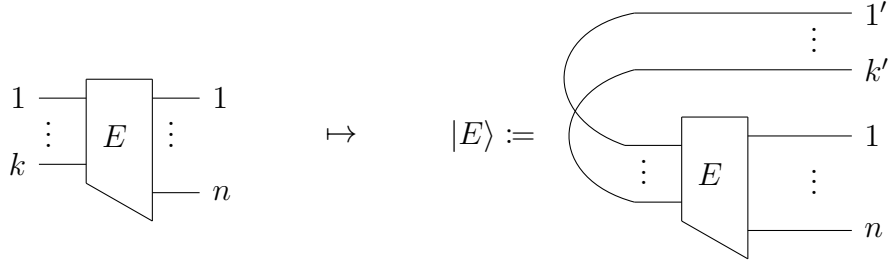


Figure A.3: Given some linear map E from k qubits to n qubits, we can transform it into a $(k+n)$ -qubit state $|E\rangle$ by applying the Choi-Jamiołkowski isomorphism.

A.1.3 The ZX and XZ Normal Forms for a CSS Code

Recall in [55], a CSS code permits a ZX normal form E_X which is constructed from the X-type stabilizer generators and the logical X operators. It also permits an XZ normal form E_Z which is constructed from the Z-type stabilizer generators and the logical Z operators.

We start by considering the maximal CSS code, which is uniquely determined by the X- and Z-type stabilizer generators.

Lemma 4. *For any maximal CSS code $|E\rangle$ over n physical qubits, its ZX normal form E_X is equivalent to its XZ normal form E_Z . In other words, E_X and E_Z correspond to the same linear map.*

Proof. Let \mathcal{S} be the maximal stabilizer group that uniquely fixes $|E\rangle$,

$$\mathcal{S} = \langle S_1^X, \dots, S_{m_1}^X, S_1^Z, \dots, S_{m_2}^Z \rangle, \quad 0 \leq m_1, m_2 \leq n, \quad m_1 + m_2 = n.$$

By Definition 4,

$$E_X = \prod_{i=1}^{m_1} (I + S_i^X) |0\rangle^{\otimes n}, \quad E_Z = \prod_{j=1}^{m_2} (I + S_j^Z) |+\rangle^{\otimes n}.$$

Note that $Z|0\rangle = |0\rangle$ and thus $S_j^Z|0\rangle^{\otimes n} = |0\rangle^{\otimes n}$. For all $1 \leq j \leq m_2$, since $[S_j^Z, S_i^X] = 0$ for all $1 \leq i \leq m_1$, we have

$$\begin{aligned} S_j^Z E_X &= S_j^Z \left(\prod_{i=1}^{m_1} (I + S_i^X) |0\rangle^{\otimes n} \right) \\ &= \prod_{i=1}^{m_1} S_j^Z (I + S_i^X) |0\rangle^{\otimes n} \\ &= \prod_{i=1}^{m_1} (I + S_i^X) S_j^Z |0\rangle^{\otimes n} \\ &= \prod_{i=1}^{m_1} (I + S_i^X) |0\rangle^{\otimes n} = E_X. \end{aligned}$$

Hence, E_X is stabilized by every Z-type stabilizer generator of \mathcal{S} . It follows that E_X is in the joint +1 eigenspace of \mathcal{S} .

Note that $X|+\rangle = |+\rangle$ and thus $S_i^X|+\rangle^{\otimes n} = |+\rangle^{\otimes n}$. Reasoning analogously, we have

$$\begin{aligned} S_i^X E_Z &= S_i^X \left(\prod_{j=1}^{m_2} (I + S_j^Z) |+\rangle^{\otimes n} \right) \\ &= \prod_{j=1}^{m_2} S_i^X (I + S_j^Z) |+\rangle^{\otimes n} \\ &= \prod_{j=1}^{m_2} (I + S_j^Z) S_i^X |+\rangle^{\otimes n} \\ &= \prod_{j=1}^{m_2} (I + S_j^Z) |+\rangle^{\otimes n} = E_Z. \end{aligned}$$

Hence, E_Z is stabilized by every X-type stabilizer generator of \mathcal{S} . It follows that E_Z is in the joint +1 eigenspace of \mathcal{S} . By the uniqueness of the maximal CSS code, $E_X = E_Z = |E\rangle$. \square

As an exercise, we use Example 8 to illustrate this proof.

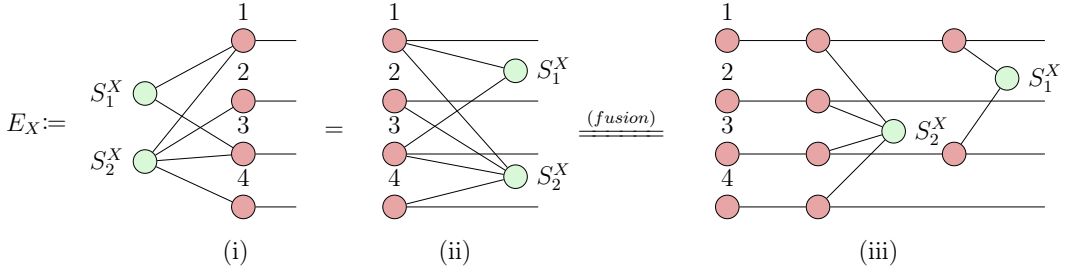
Example 8. Consider a maximal stabilizer group $\mathcal{S} = \langle S_1^X, S_2^X, S_1^Z, S_2^Z \rangle$, where

$$S_1^X = X_1 X_3, \quad S_2^X = X_1 X_2 X_3 X_4, \quad S_1^Z = Z_2 Z_4, \quad S_2^Z = Z_1 Z_2 Z_3 Z_4.$$

Let $|E\rangle$ be the maximal CSS code uniquely fixed by \mathcal{S} . Let E_X and E_Z be its ZX and XZ normal forms respectively. Then $E_X = E_Z$.

Proof. According to Definition 4, E_X is defined by the X-type stabilizer generators. In Figure A.4, after relocating the Z spiders, E_X in (i) is transformed into a semantically equivalent diagram in (ii). After unfusing the wires and applying Definition 9,

$$E_X = \sum_{b \in V} |b\rangle, \quad V = \text{Span}\{v_1, v_2\}, \quad v_1 = \begin{bmatrix} 1 \\ 0 \\ 1 \\ 0 \end{bmatrix}, \quad v_2 = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}.$$

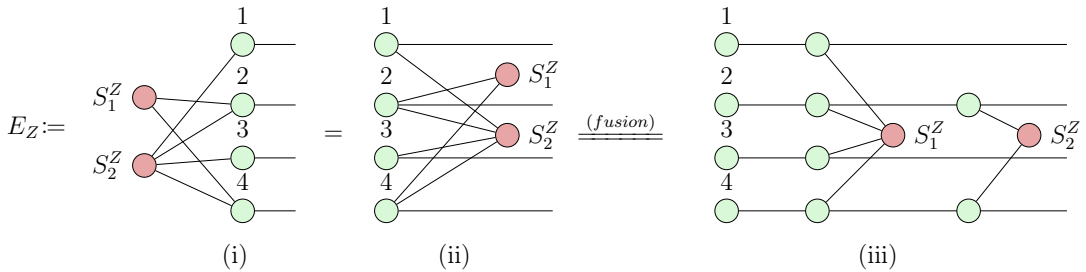


$$\underline{\underline{\text{Definition}}} \quad (I + S_2^X)(I + S_1^X)|0000\rangle = \sum_{i,j=0}^1 (S_2^X)^j (S_1^X)^i |0000\rangle = \sum_{b \in V} |b\rangle$$

Figure A.4: The ZX normal form of the maximal CSS code fixed by \mathcal{S} . The equalities hold up to a scalar.

Similarly, E_Z is defined by the Z-type stabilizer generators. In Figure A.5, after relocating the X spiders, E_Z in (i) is transformed into a semantically equivalent diagram in (ii). After unfusing the wires and applying Definition 9,

$$E_Z = \sum_{b \in W} |b\rangle, \quad W = \text{Span}\{w_1, w_2\}, \quad w_1 = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}, \quad w_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \\ 1 \end{bmatrix}.$$



$$\underline{\underline{\text{Definition}}} \quad (I + S_2^Z)(I + S_1^Z)|++++\rangle = \sum_{i,j=0}^1 (S_2^Z)^j (S_1^Z)^i |++++\rangle = \sum_{b \in W} |b\rangle$$

Figure A.5: The XZ normal form of a maximal CSS code fixed by \mathcal{S} . The equalities hold up to a scalar.

By direct computation, we can show that up to a scalar, $E_Z = E_X$:

$$\begin{aligned}
E_Z &= (I + S_2^Z)(I + S_1^Z)|++++\rangle \\
&= (I + S_2^Z)(I + S_1^Z) \sum_{v \in \mathbb{F}_2^4} |v\rangle \\
&= (I + S_2^Z) \sum_{v \perp w_1} |v\rangle, \quad \text{where } S_1^Z = \bigotimes_{t=1}^n Z^{(w_1)_t} \\
&= \sum_{v \perp w_1, v \perp w_2} |v\rangle, \quad \text{where } S_2^Z = \bigotimes_{t=1}^n Z^{(w_2)_t} \\
&= \sum_{c \perp c'} |c\rangle, \quad \forall c' \in W, \quad \text{where } W = \text{Span}\{w_1, w_2\} \\
&= \sum_{b \in V} |b\rangle, \quad \text{where } V = \text{Span}\{v_1, v_2\} \\
&= E_X.
\end{aligned}$$

□

Proposition 4. For any non-maximal CSS code \mathcal{C} over n physical qubits, its ZX normal form E_X is equivalent to its XZ normal form E_Z . In other words, E_X and E_Z correspond to the same linear map.

Proof. Suppose towards contradiction that E_X and E_Z correspond to different linear maps. After bending the input wires of E_X and E_Z and turning them into the output wires, we obtain a maximal CSS code whose ZX and XZ normal forms are E'_X and E'_Z respectively. Since $E_X \neq E_Z$, $E'_X \neq E'_Z$. By Lemma 4, $E'_X = E'_Z$. This yields a contradiction. Therefore, $E_X = E_Z$. □